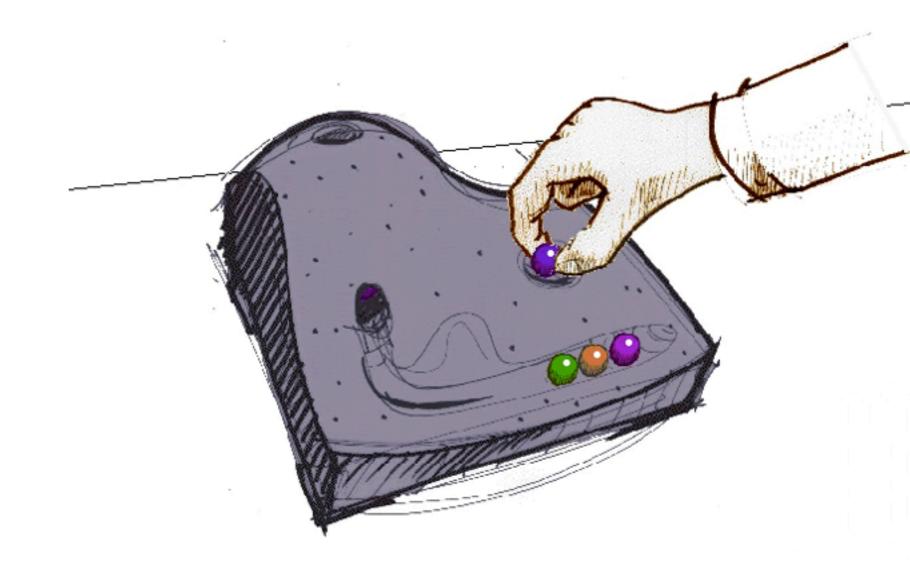
Advanced Human-Computer Interaction: Tangible Interaction

Céline Coutrix http://iihm.imag.fr/coutrix/ Celine.Coutrix@imag.fr

Course objectives

- Answering basic questions, i.e.:
 - What are TUI?
 - What is their story?
 - What are they good for?
 - What are their limitations? + Research areas
- Building TUI

Interfaces involving physical objects that can be grasped



Example: Durell Bishop's Answering Machine



Graphical User Interfaces

interfaces usually limited to std screen+keyboard+mouse

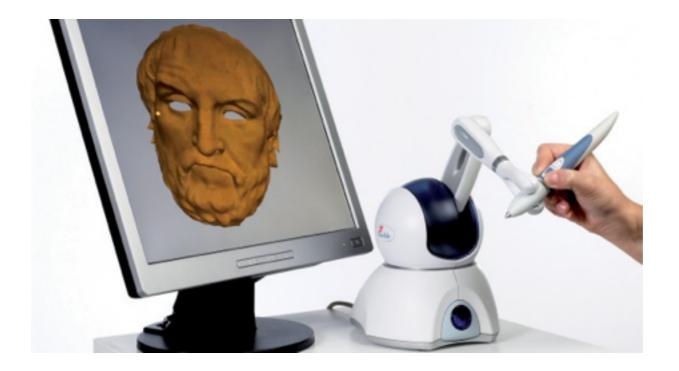


Virtual Reality Interfaces

interfaces to immerse the user in a digitally generated world



Augmented Reality (AR) and Augmented Virtuality (AV) Tangible Interfaces belong to AR+AV



Haptic Interaction

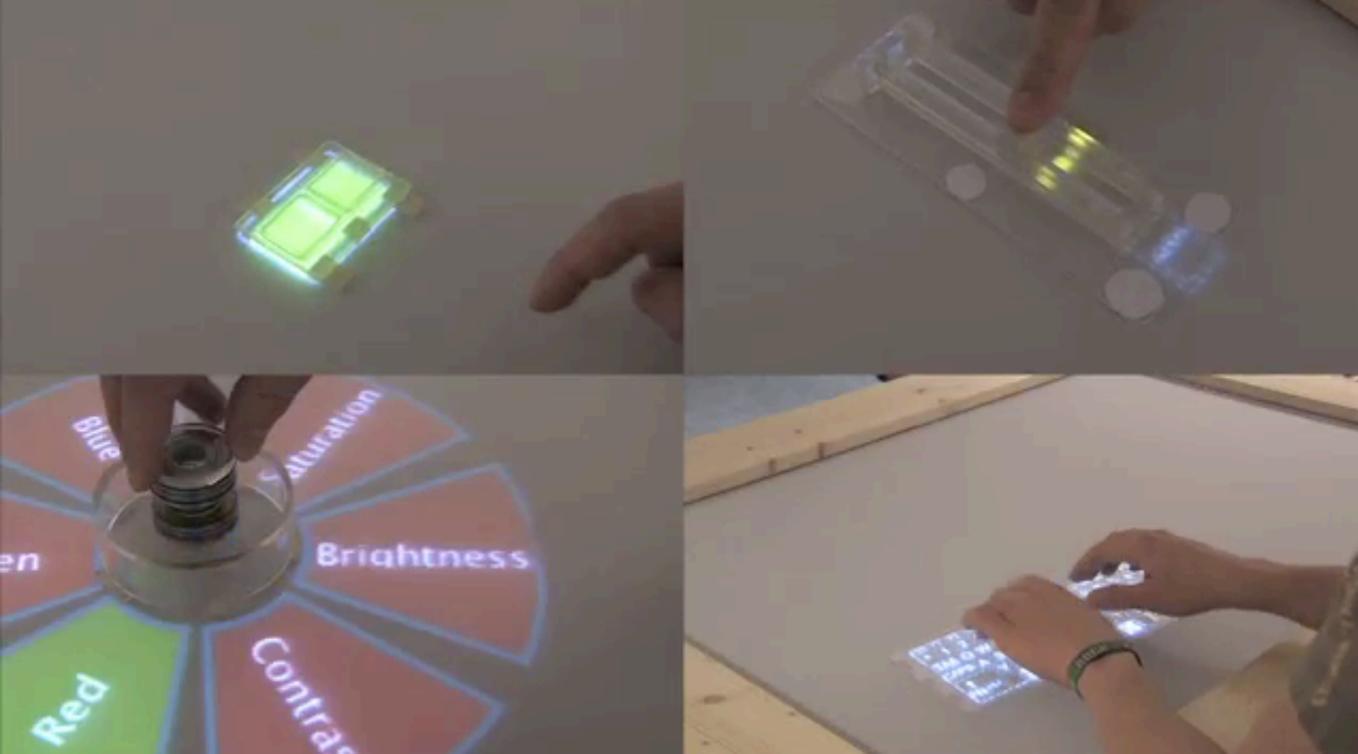
Tangible Interfaces belong to Haptic: Both involve touch and manipulation, but haptic usually not passive



Internet of Things

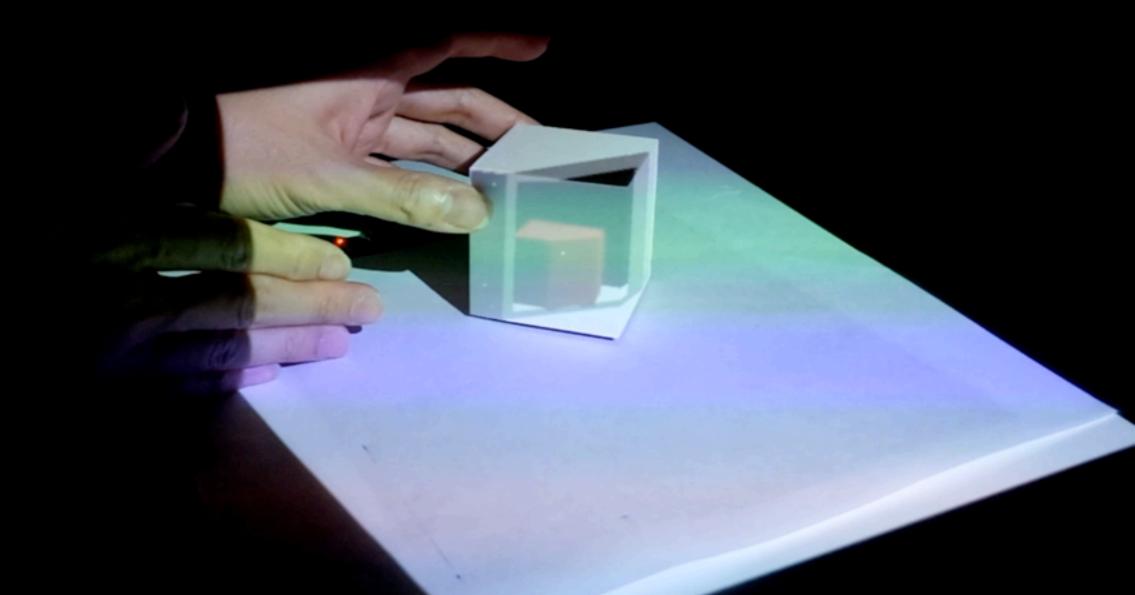
TUI not necessarily connected to Internet If so, can be through a computer

Spread: GUI paradigm

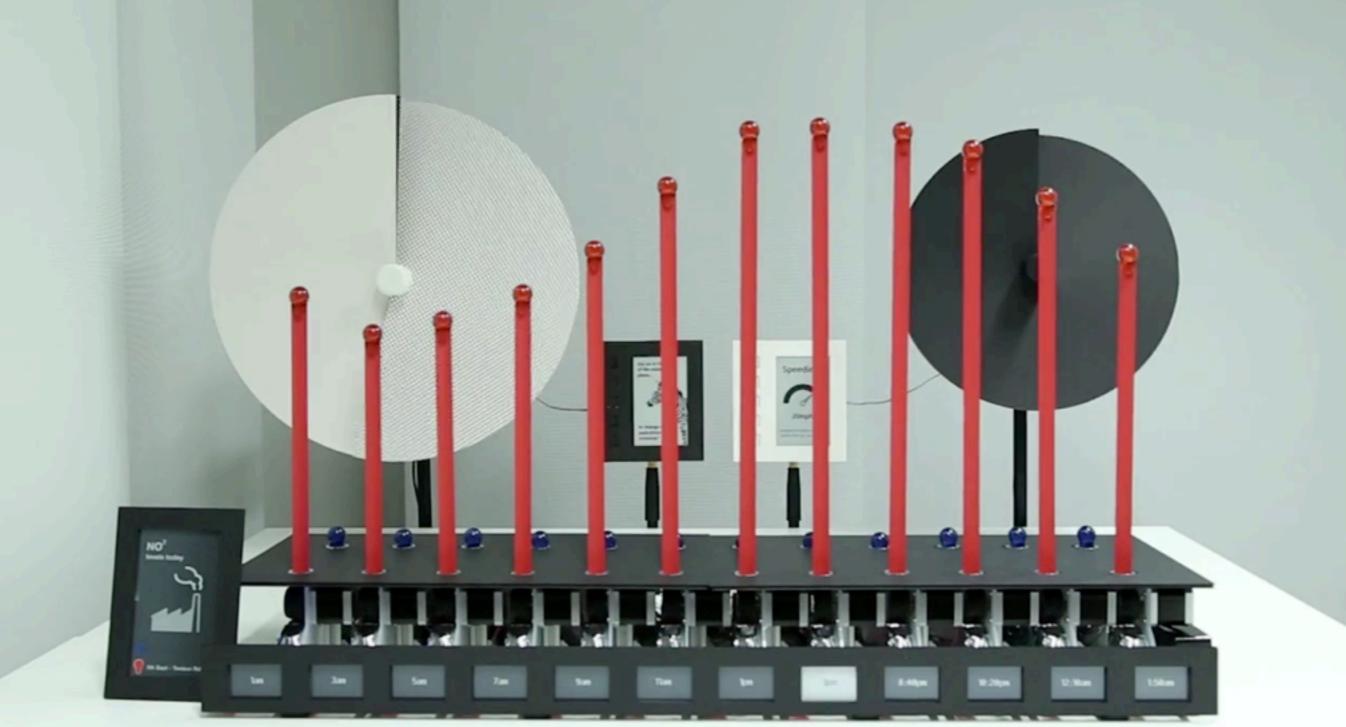


Spread: Augmented Reality paradigm

Section Cut to See Inside



Spread: visualisation tasks



Spread: Remote collaboration tasks

Connected Tangible Tokens with Shape Output

What is their story?

Manipulation of tangible tools has always been here...

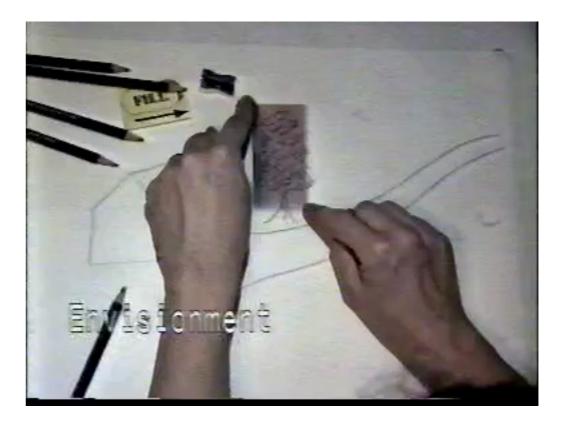


... and is still here



Seminal papers





Early works on Tangible User Interfaces

- DataTiles: Tangible overlay mixing Tangible and Graphical Interaction
 - https://www.youtube.com/watch?v=cmD8EKWxD4M
- Containers: mediaBlocks
 - http://vimeo.com/48827402
- metaDesk:
 - http://vimeo.com/44545109
- 3D animation with tangible sliders (1996):
 - https://www.youtube.com/watch?v=SnDHjY5aD5c

Example of Tangible User Interfaces





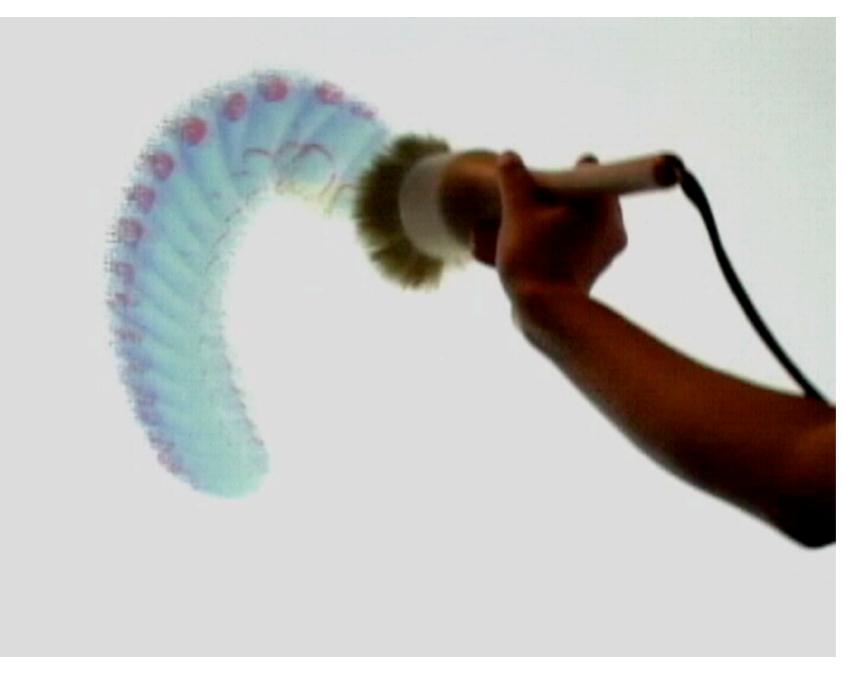
http://dl.acm.org/citation.cfm? doid=1125451.1125582

Example of Tangible User Interfaces



https://www.youtube.com/watch?v=0h-RhyopUmc https://www.youtube.com/watch?v=MPG-LYoW27E

Example of Tangible User Interfaces



I/O Brush

Tangible User Interfaces What are they good for?

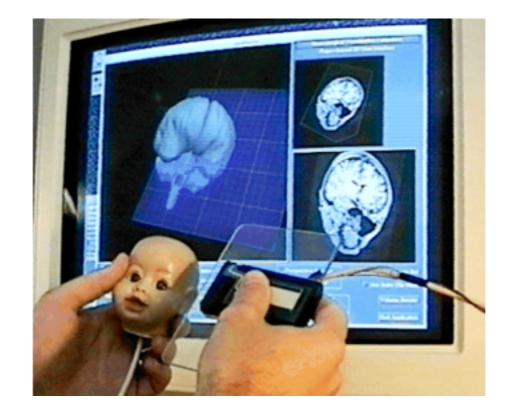
Tangible User Interfaces What are they good for?

 Interaction embodied in the physical world of the user: Physical User & Physical Interface

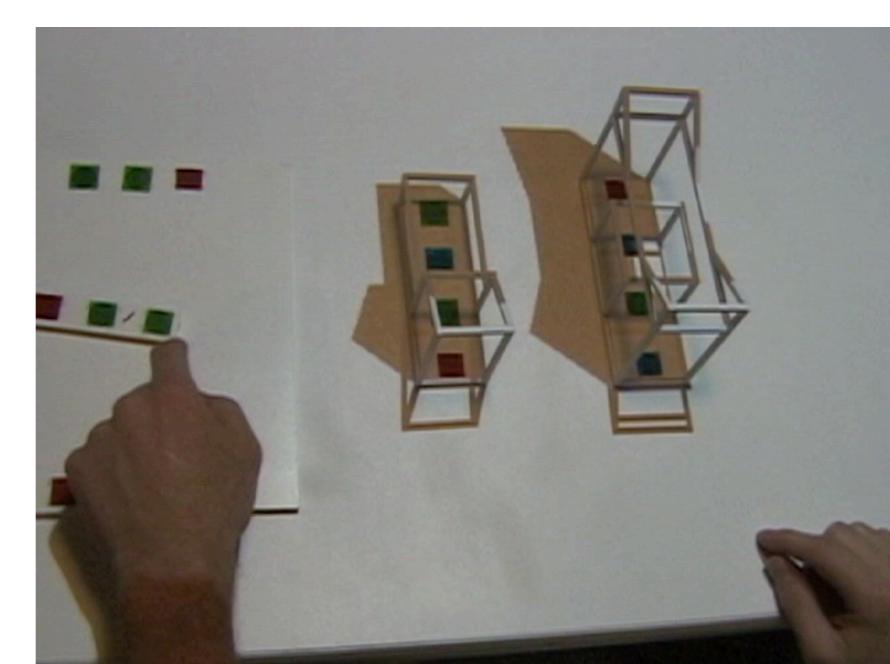
Performance:

passive haptic feedback

Object (prop) to interact at a distance with GUI

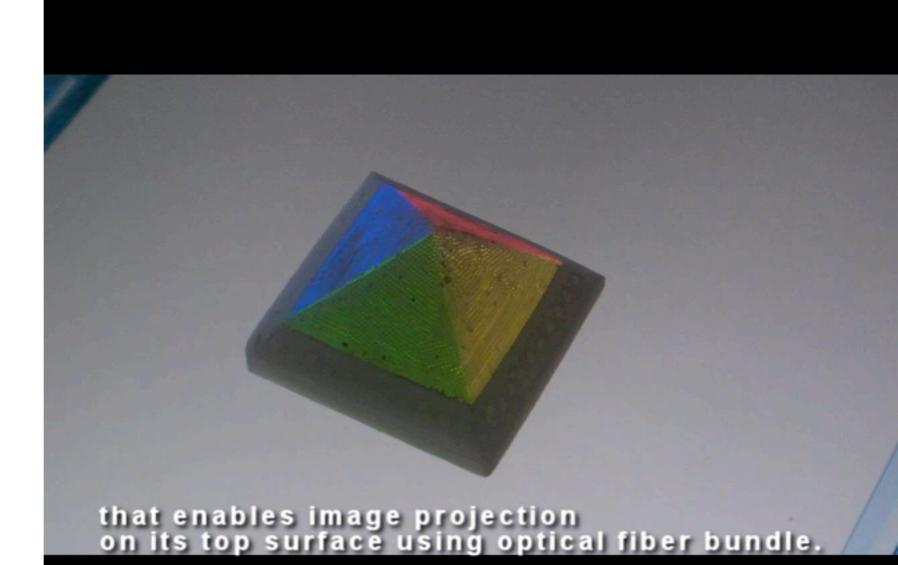


Tangible and overlaid projection



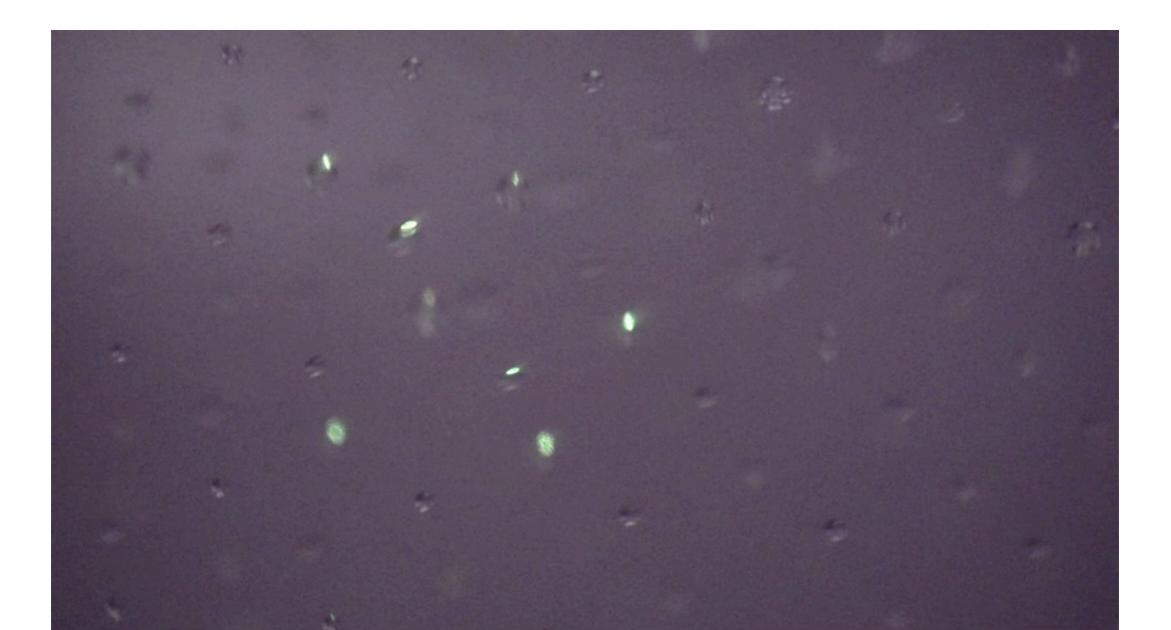
Example: URP

Rear-projection and optical fibers



Example: Ficon

Printed Optics



- **None** = No analogy between action and result
 - E.g., command-line UI, clock in URP

- Noun = shape-related: "an <X> in the system is like an <X> in the real world"
 - E.g., dictionary (http://dl.acm.org/citation.cfm? doid=302979.303111)

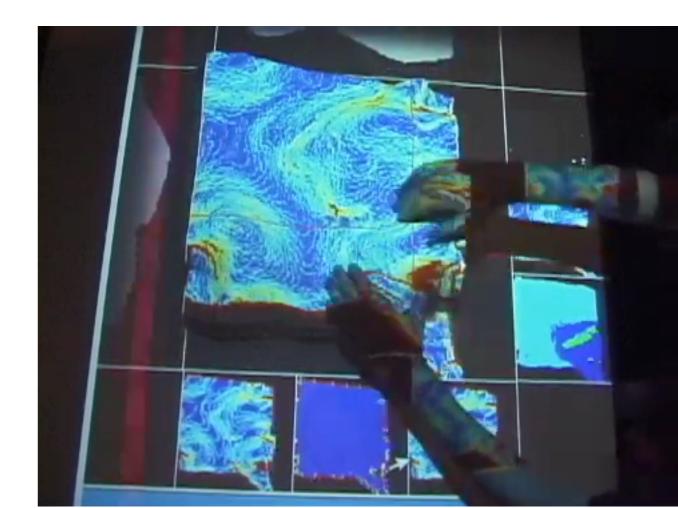


- Verb = motion-related: "<X>-ing in our system is like <X>-ing in the real world"
 - E.g., NAVRNA



- Noun & Verb = "<X>-ing an <A> in our system is like
 <X>-ing something <A>-ish in the real world"
 - E.g., eraser in Digital Desk, building in URP

- **Full** = In user's mind, there is no system
 - E.g., Illuminating Clay



Tangible User Interfaces What are they good for?

HMM

- Interaction embodied in the physical world of the user: Physical User & Physical Interface
- Performance:

passive haptic feedback

Tangible User Interfaces: What are they good for?

Several experiments demonstrated their benefits

Tangible User Interfaces: Benefit over GUI

- Time-multiplexed vs. Space-multiplexed input: inter-device transaction phases
- Specialized vs. Generic form-factor

Tangible User Interfaces: Benefit over GUI

• Time-multiplexed vs. Space-multiplexed input: inter-device transaction phases

GUI	TUI
Acquire physical device	Acquire physical device
Acquire logical device	
Manipulate logical device	 Manipulate logical device

Task: continuously track four targets moving randomly on the screen (compound tasks)

- Rotor: position and rotation
- Brick: position and rotation
- Strechable square: position, rotation and scale
- Ruler: position, rotation and scale



Space-multiplexed Specialized Space-multiplexed Generic Time-multiplexed

Does the **physical switching** cost more than the **logical switching** between tools?



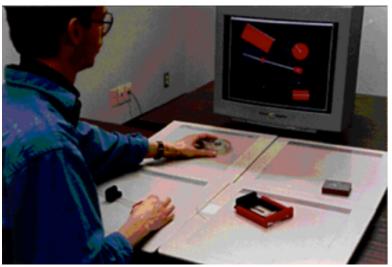
Space-multiplexed Specialized Space-multiplexed Generic Time-multiplexed

Does the **physical switching** cost more than the **logical switching** between tools?

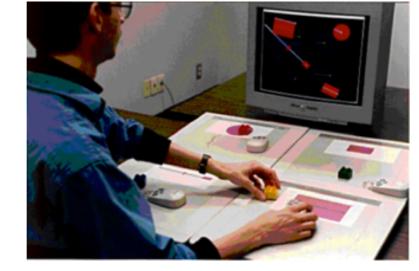
Is the **specialized** input useful?



Space-multiplexed Specialized Space-multiplexed Generic Time-multiplexed



Space-multiplexed Specialized **performs best**



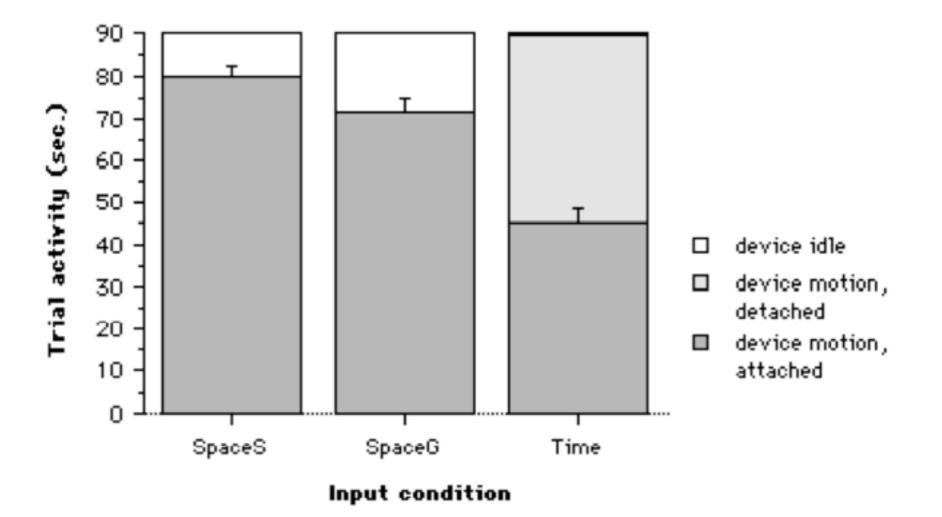
Space-multiplexed Generic performs better than Time-multiplexed but worst than Specialized

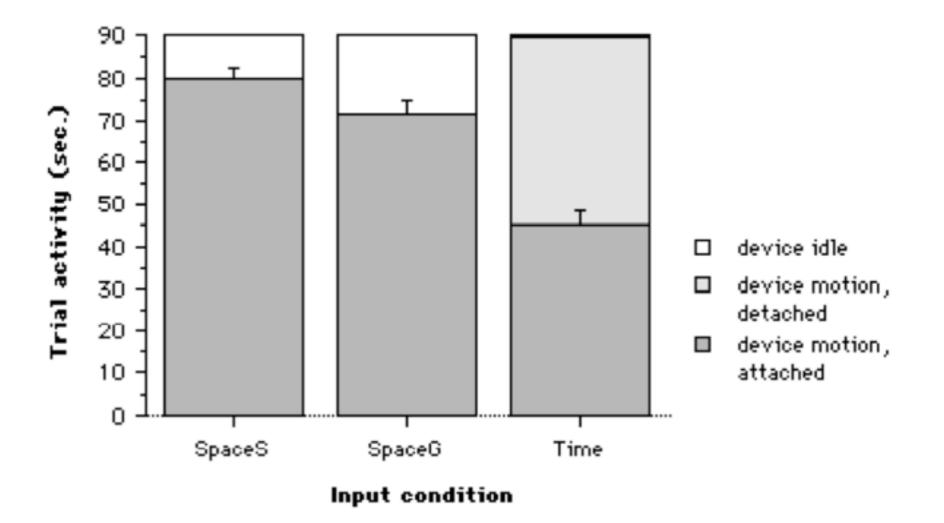


Time-multiplexed

performs worst

- Consistent across the 4 devices
- (Score based on root mean square errors of all dimensions (position, orientation and scale if applicable) of all devices)





Users spend more time switching between tools with time-multiplexed UI rather than with space-multiplexed UI

- 1. Space-multiplexed > Time-multiplexed input:
 - Persistance of attachement between physical and logical (software, graphical) controllers
 - Parallel 2-handed vs.
 Sequential 1-handed interaction
- 2. Specialized vs. Generic form-factor
 - Visual and tactile reminder

Tangible User Interfaces: What are they good for?

Several experiments demonstrated their benefits

What about multitouch input?

What about multitouch input?

also space-multiplexed

Two experiments

Acquisition



Manipulation

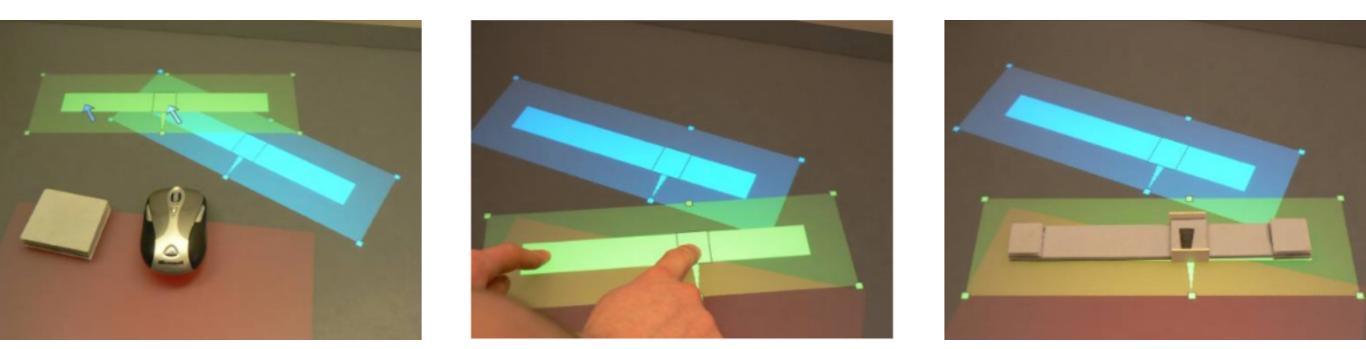


Manipulation



Assumes users already acquired the control widget

Task: match position+orientation+cursor of blue object manipulating yellow object as quickly as possible



Multitouch

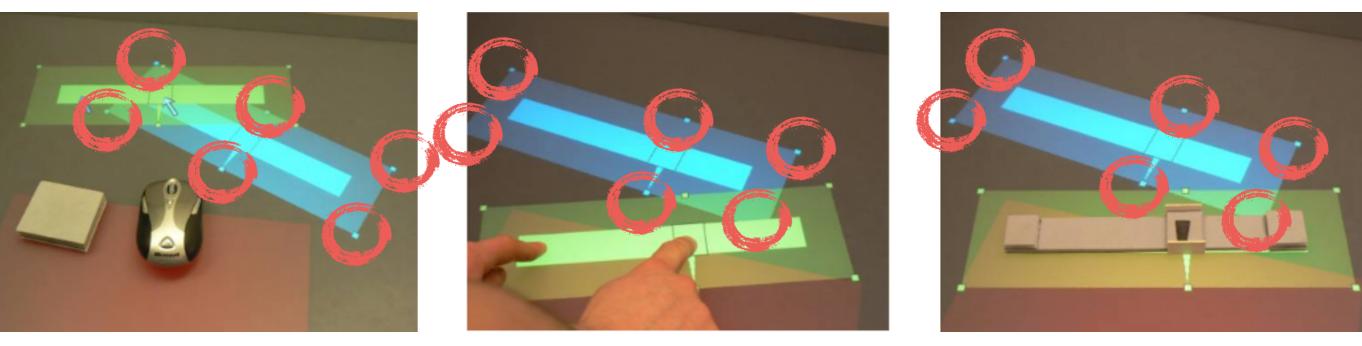
Mouse+Puck



(all conditions sensed through multitouch table)

Task: match position+orientation+cursor of blue object manipulating yellow object as quickly as possible

±5px

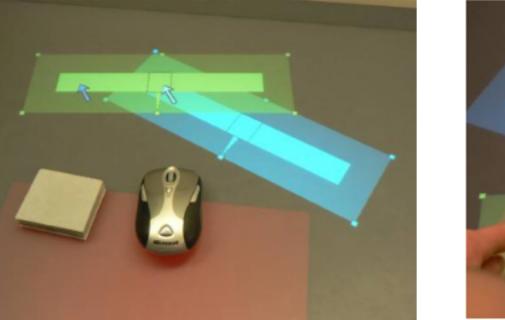


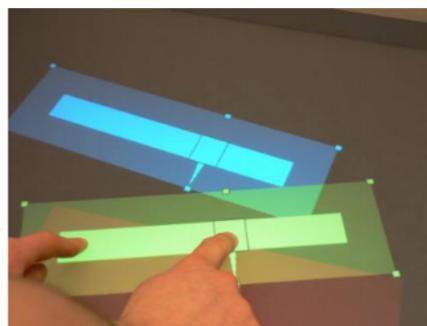
Mouse+Puck

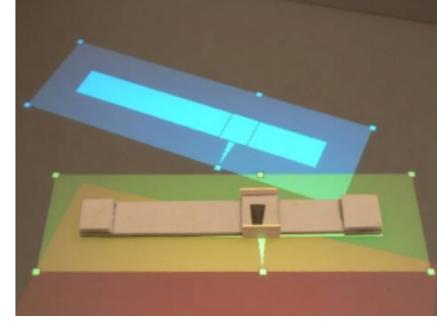
Multitouch

Tangible

Measures: Time to complete matching task Subjective comfort Subjective ease of use



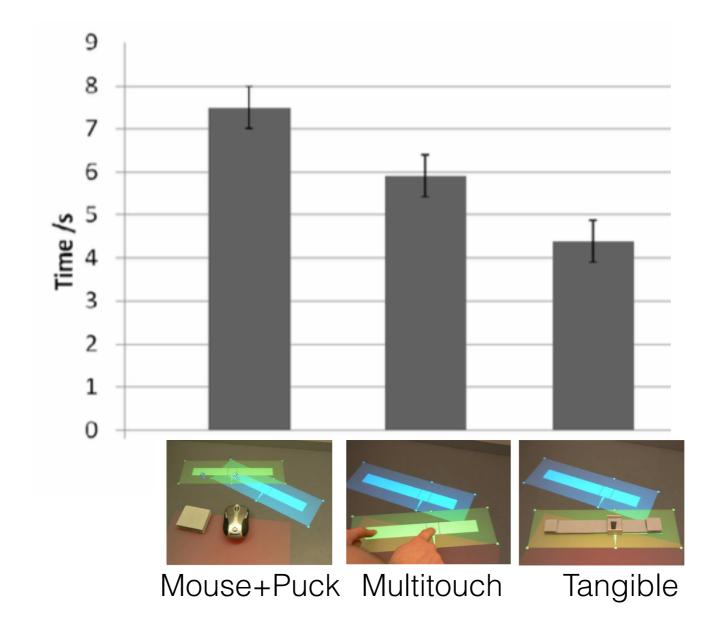


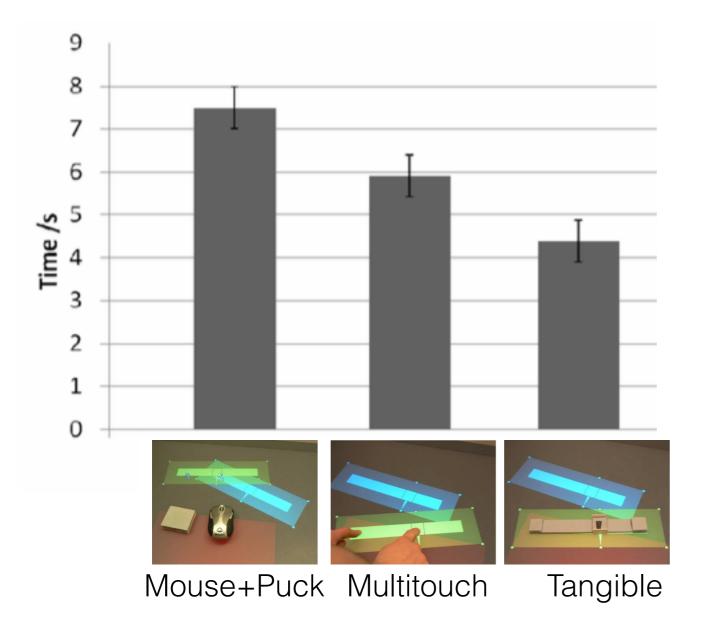


Multitouch



Mouse+Puck





+ Little difference in comfort and ease of use

A participant: « better degree of control with tangibles, especially when rotating »

Manipulation



Two experiments

Acquisition



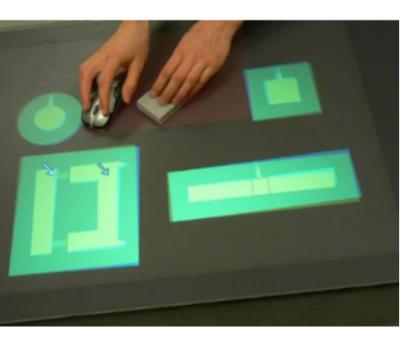
Manipulation

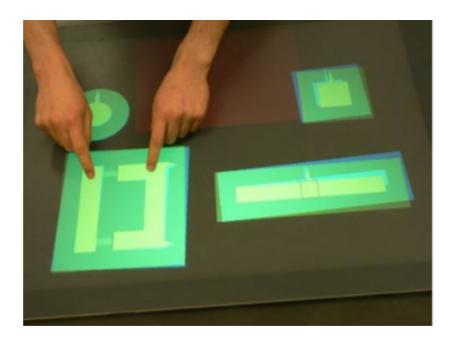


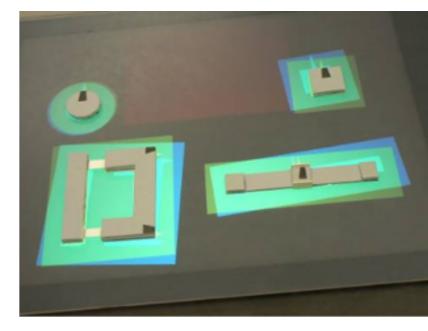
Acquisition



Task: match position+orientation+cursor of blue objects manipulating yellow objects at all times





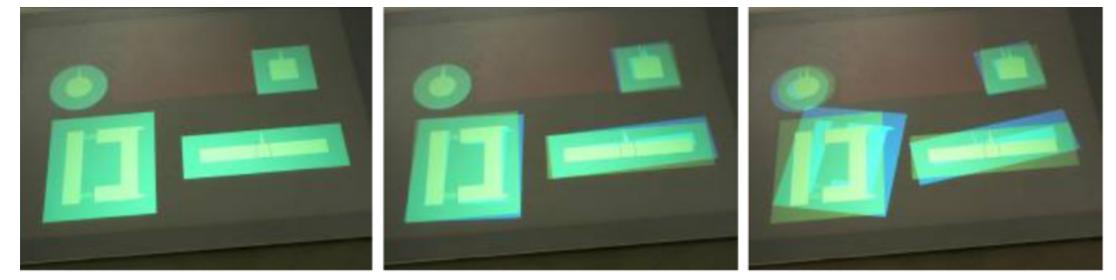


Mouse+Puck

Multitouch



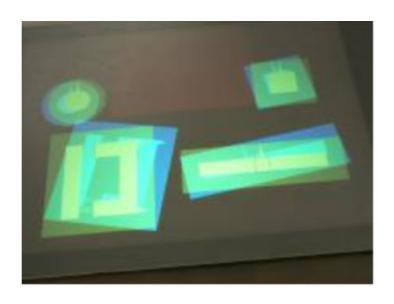
(all conditions sensed through multitouch table)



Task: match position+orientation+cursor of blue objects manipulating yellow objects at all times

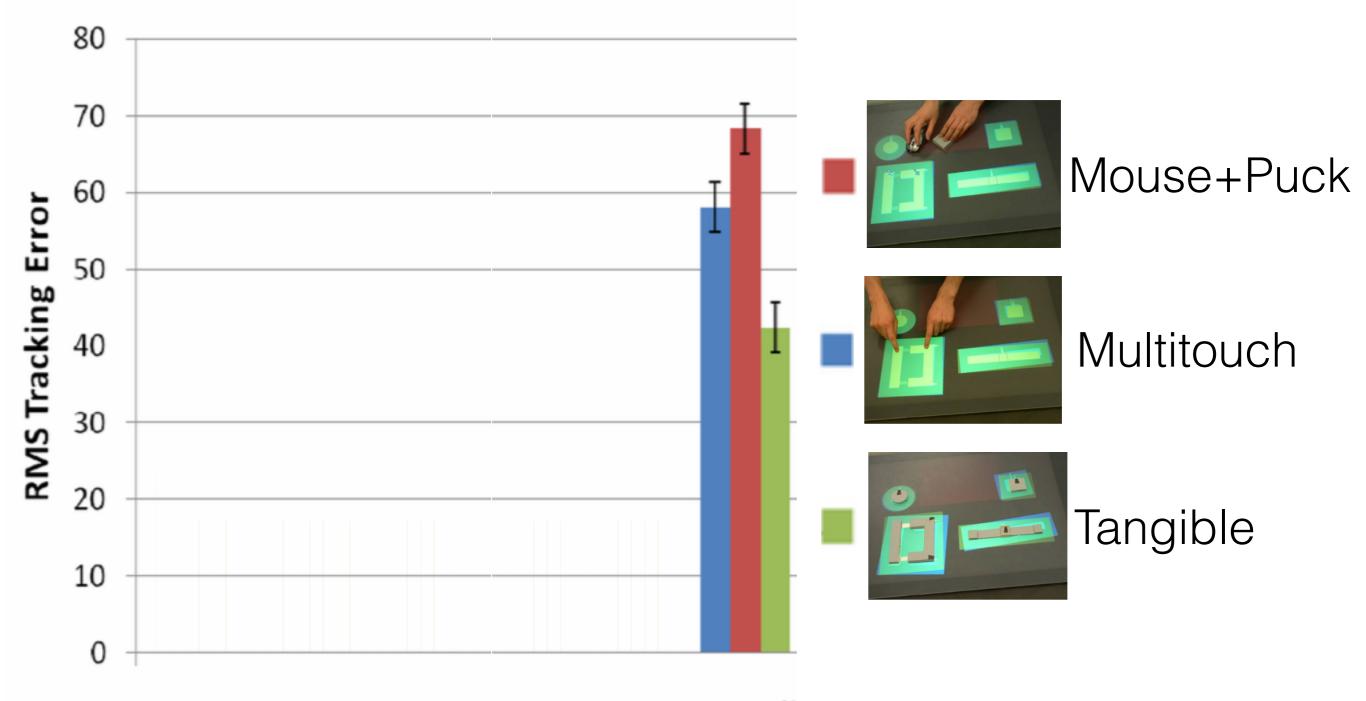
 \Rightarrow move between widgets \Rightarrow many (re)acquisitions

time

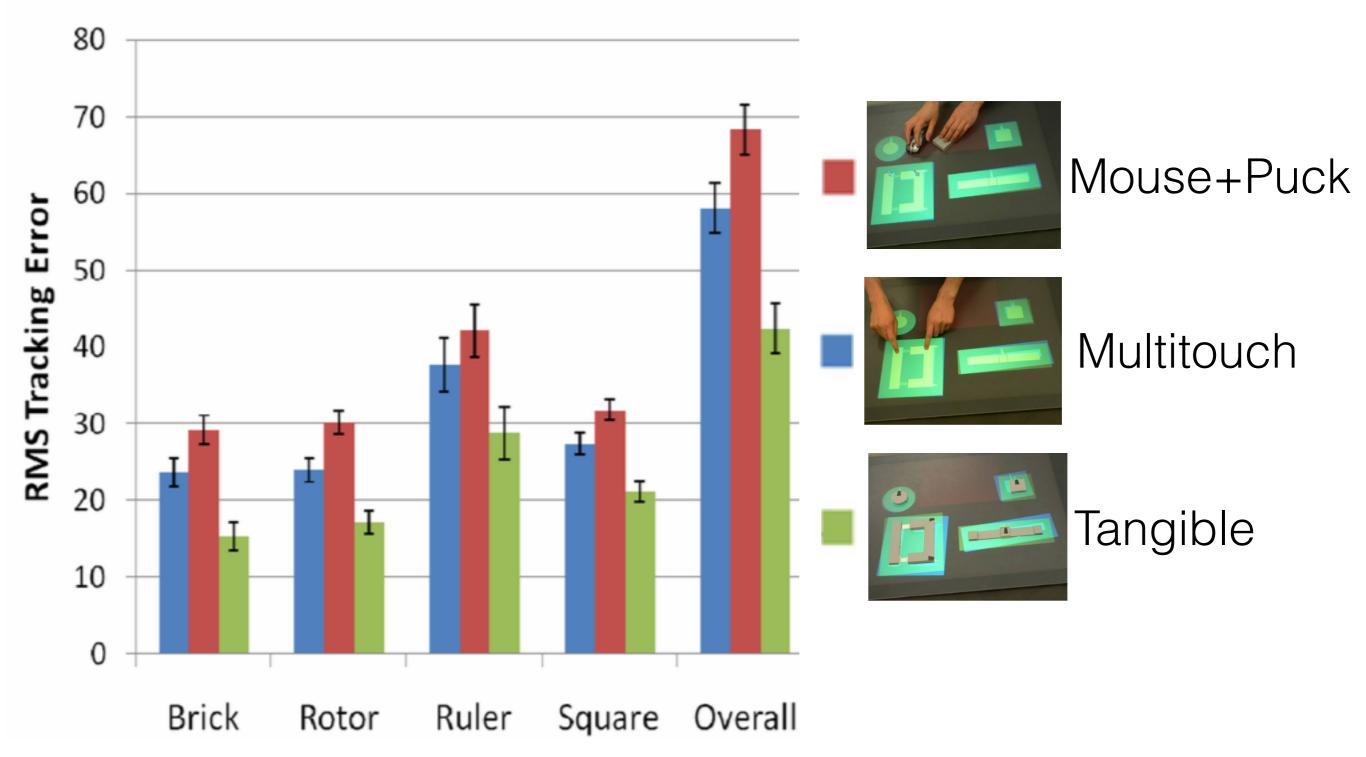


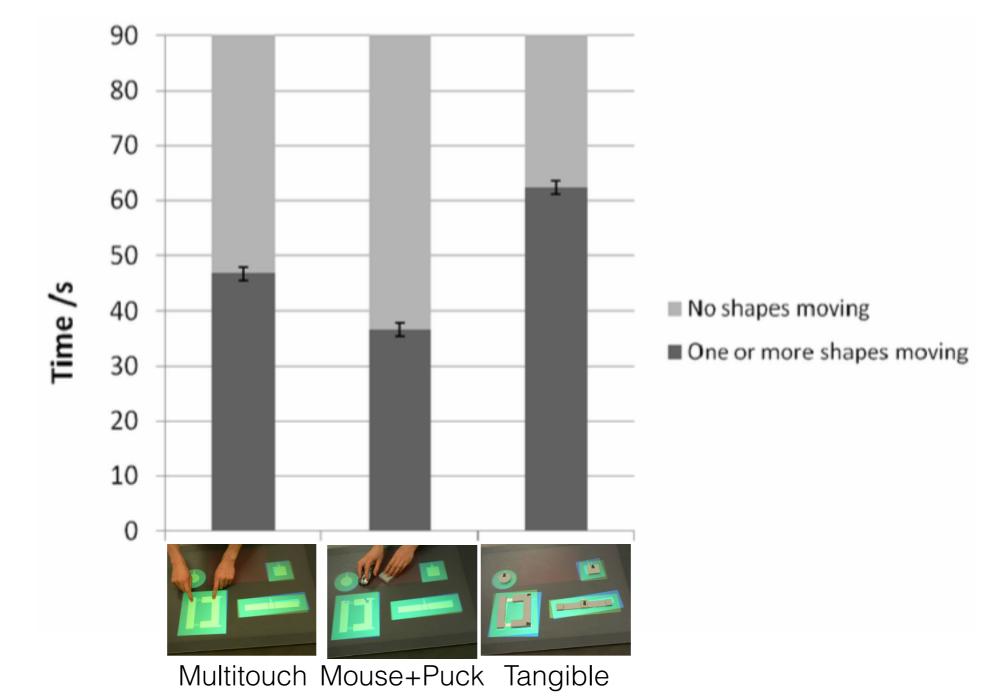
Measures: root-mean-square errors of all dimensions (position, orientation and scale or cursor position if applicable) of all devices

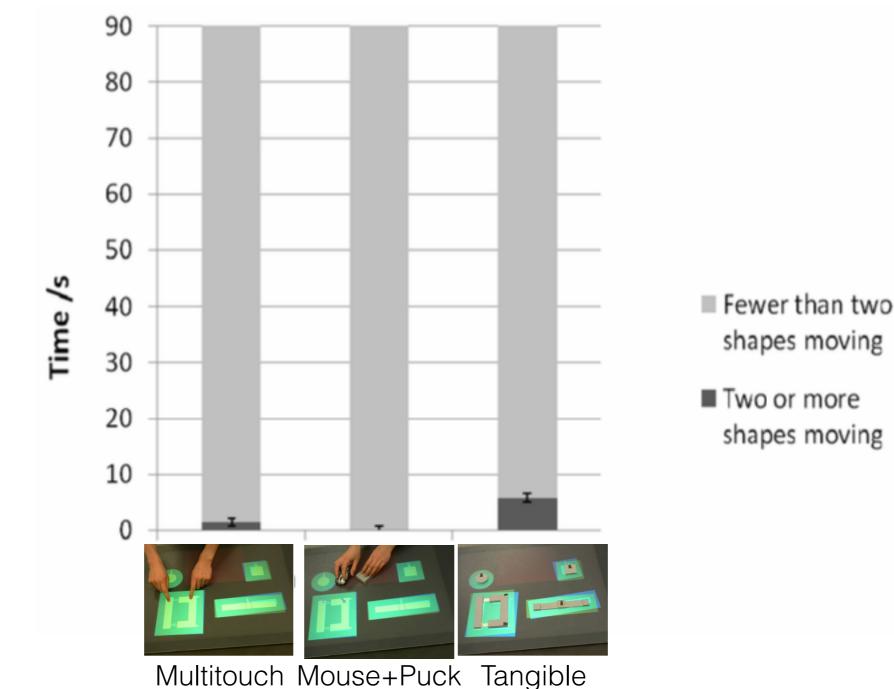
+ subjective preference, confort and ease of use

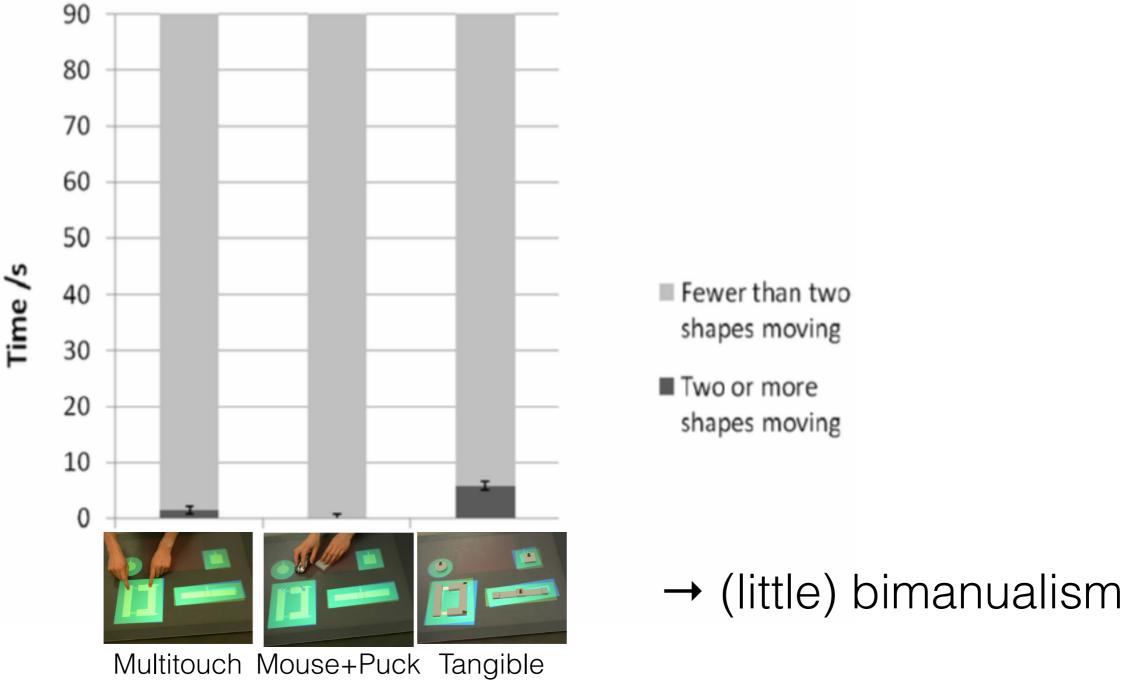


Overall





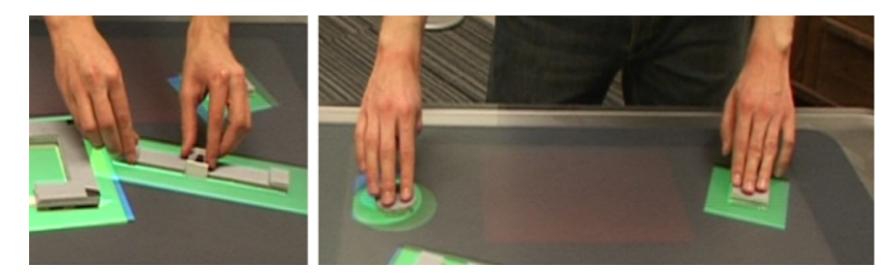


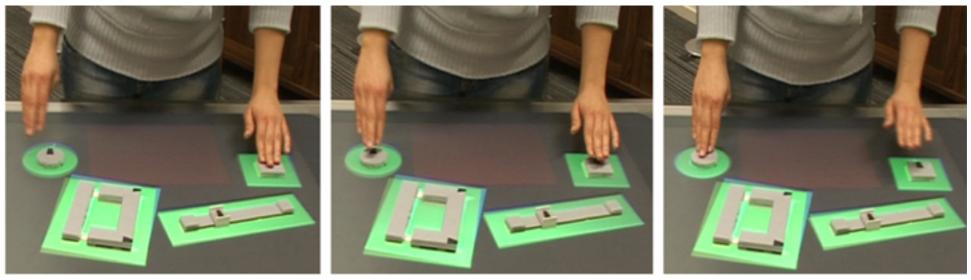


+ Little difference in preference, comfort and ease of use

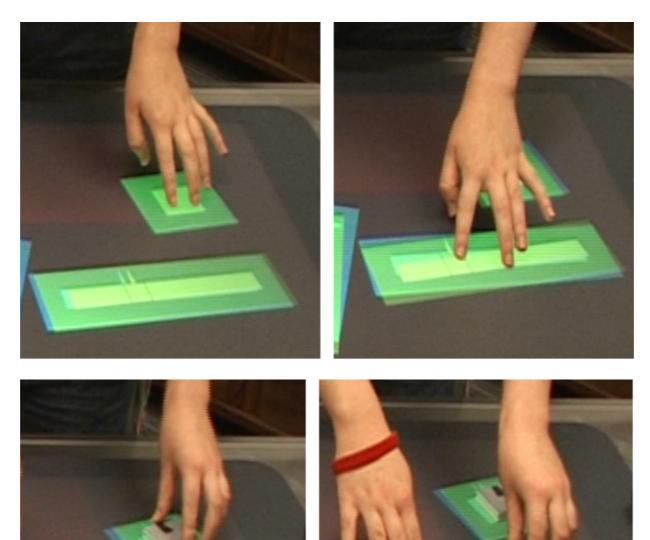


Multitouch Mouse+Puck Tangible

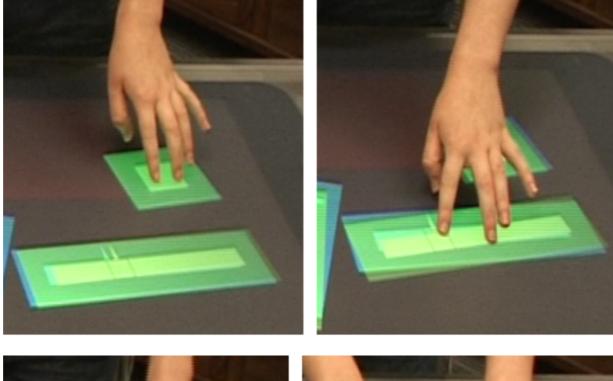




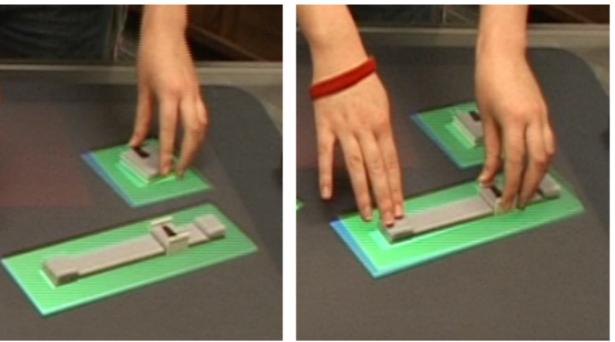
Same pattern for multitouch and tangible



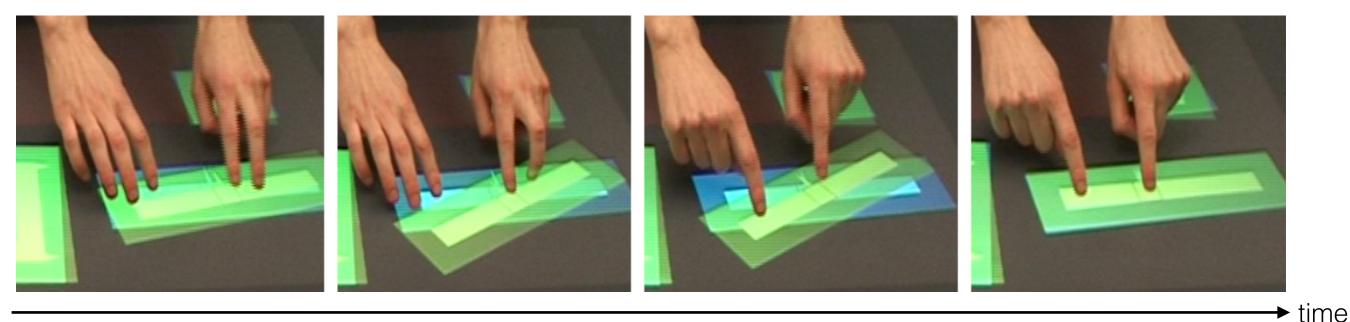
multitouch ≠ tangible



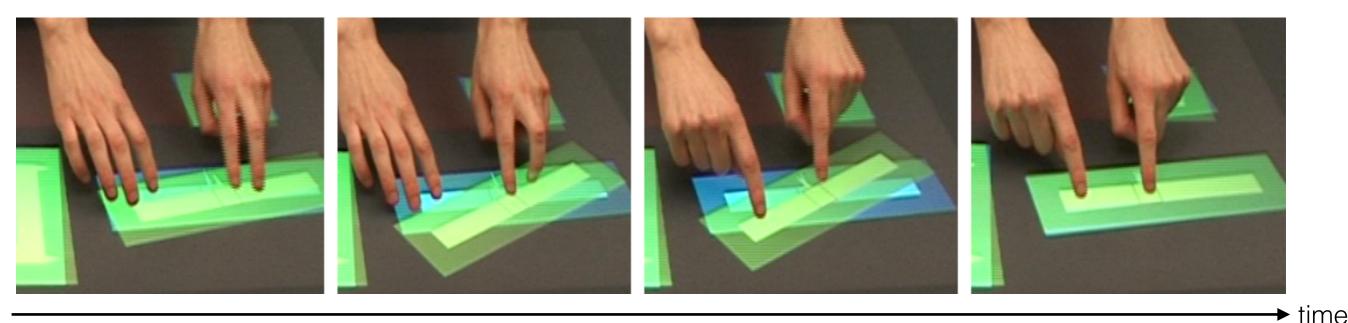
number of contact points



multitouch ≠ tangible



multitouch: number of contact points



multitouch: number of contact points decrease \Rightarrow more accurate

tangible: number of contact points increase \Rightarrow more accurate

+ greater variability within and between participants

Tangible User Interfaces: What are they good for?

Several experiments demonstrated their benefits

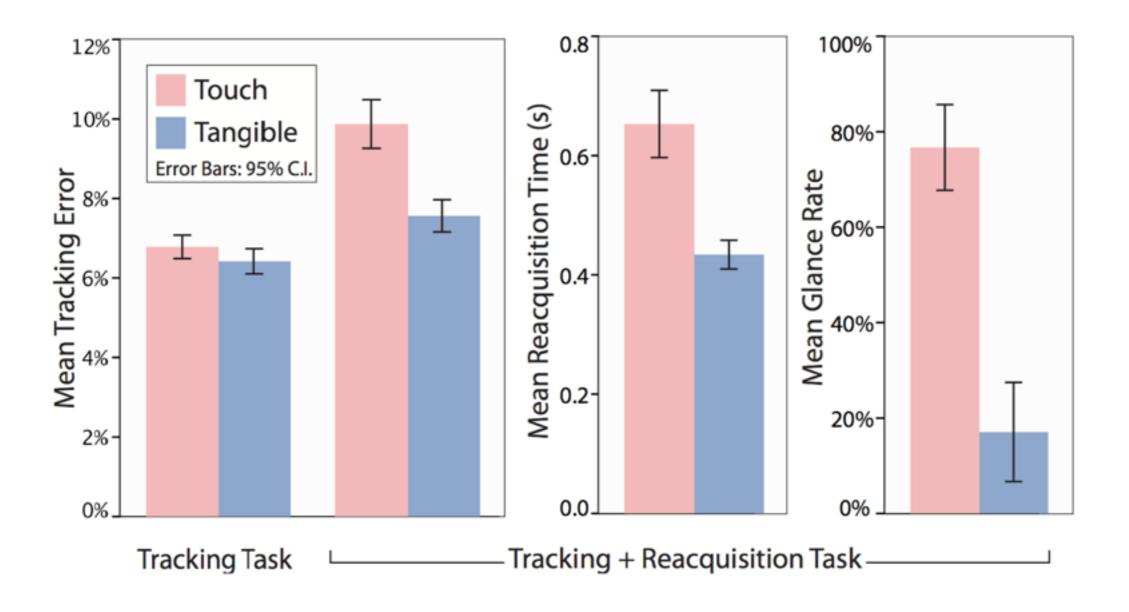
Tangible User Interfaces: Benefit for distant interaction

- Techniques: Touch vs. Tangible slider
- Tasks: Tracking vs. Tracking + additional tapping



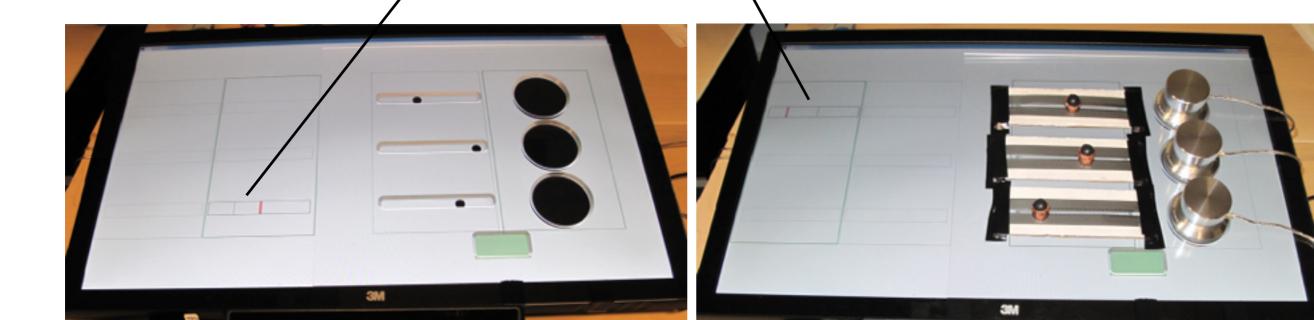
Tangible User Interfaces: Benefit for distant interaction

Comparing touch and tangible interaction



Several experiments demonstrated their benefits

Tasks: set horizontal position of cursor

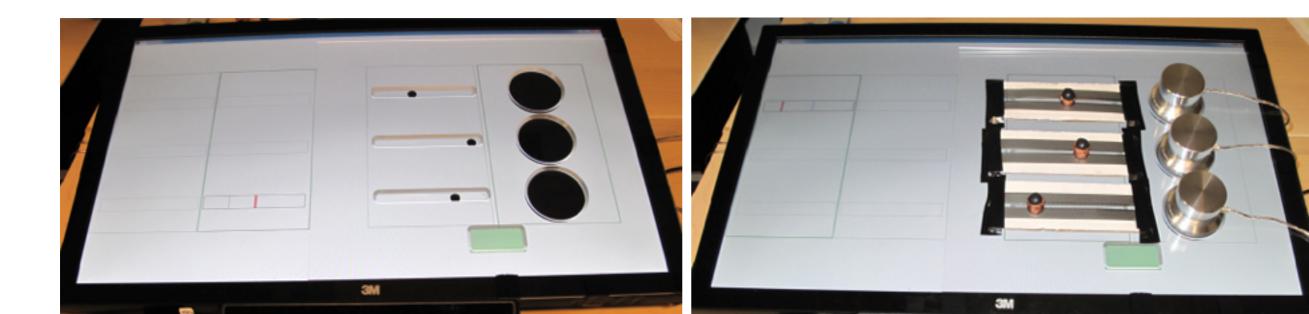


Tasks: set horizontal position of cursor

- Press green button; Acquisition of required tool; Move towards and stay in target for 1 second;
- 2. Move cursor back and forth 5 times between two targets



	Touch	Overlay	Tangible
Slider			
Single-turn dial			
Multi-turn dial (Task 2 only: with CD gain 3x)			



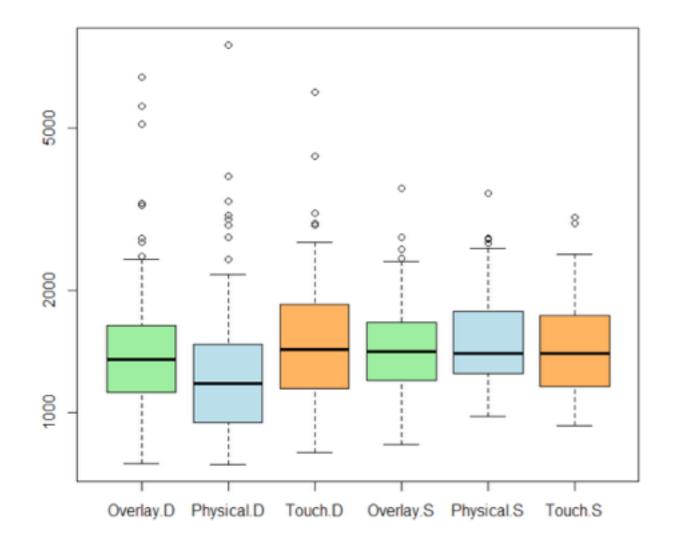
• Task 1: acquisition and movement

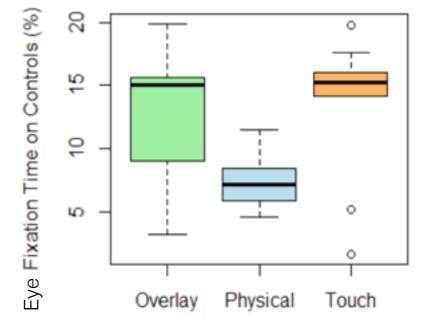
	Touch	Overlay	Tangible
Slider		2	
Single-turn dial		-	

• Task 2: repetitive task

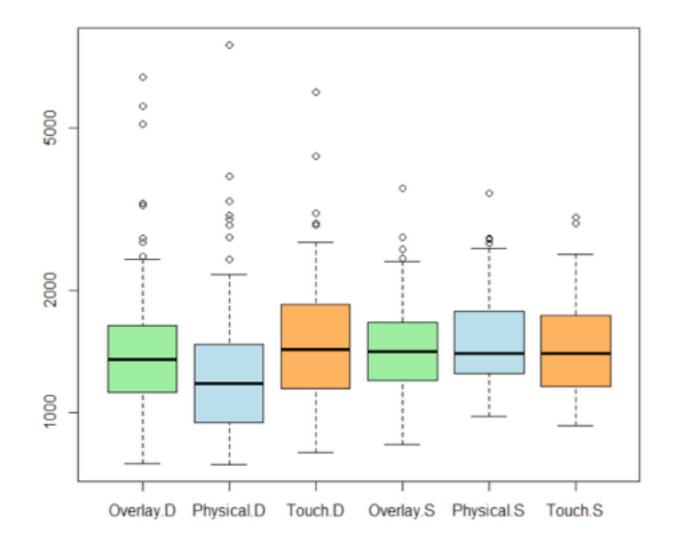
	Touch	Overlay	Tangible
Slider			
Single-turn dial		7	
Multi-turn dial (with CD gain 3x)			

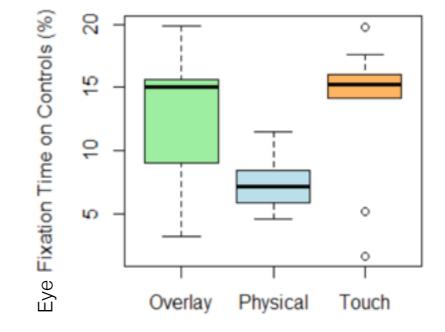
Task 1: acquisition and movement





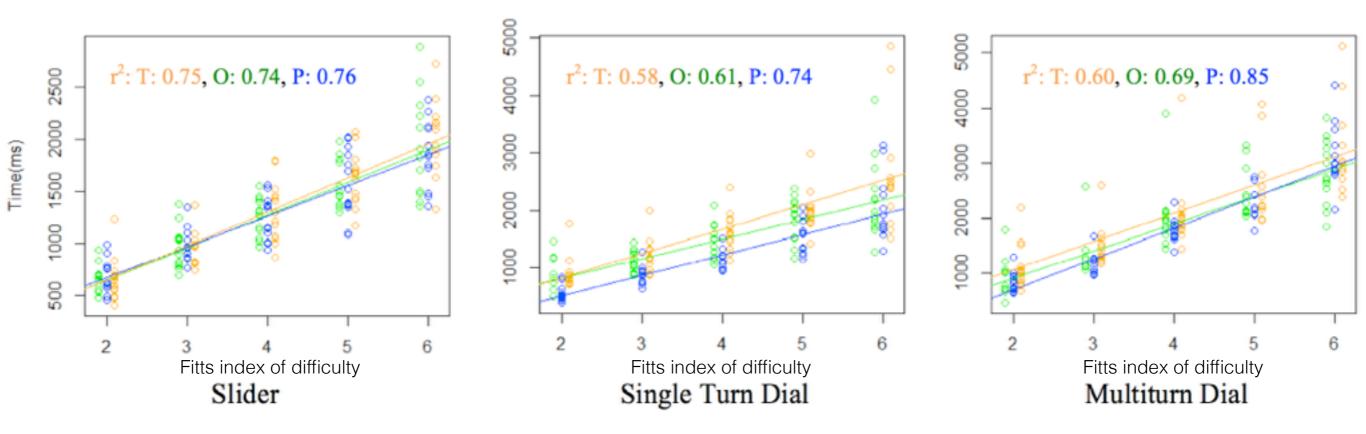
Task 1: acquisition and movement



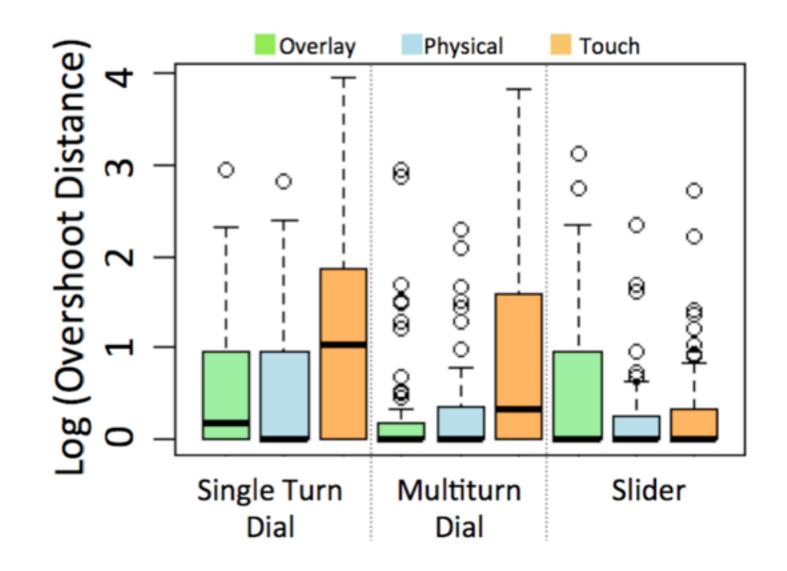


No difference found for sliders: because of manipulation problem with tangible sliders: *"participants complained that they were wobbly* and required some pressure"

Task 2: Repetitive movement



Task 2: Repetitive movement

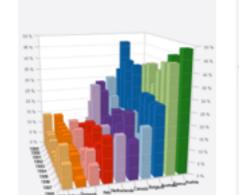


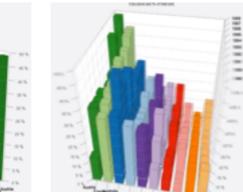
Several experiments demonstrated their benefits

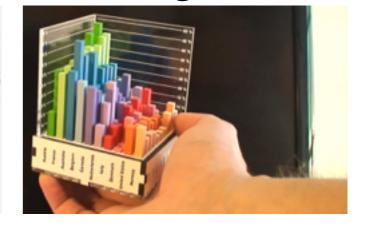
3D Mono 3D Stereo



2D







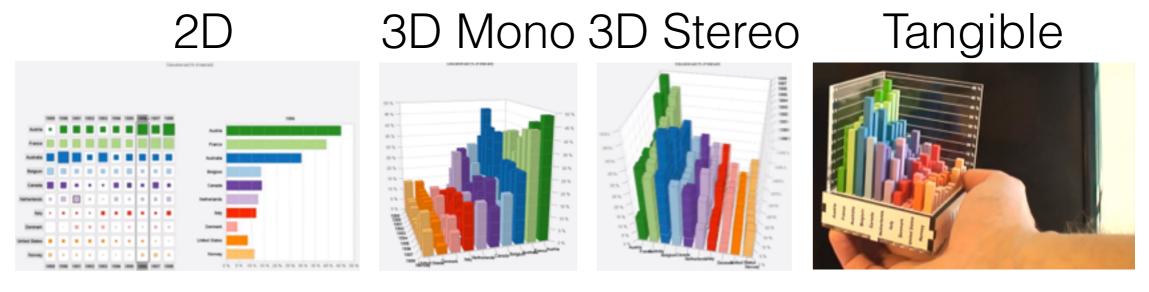
Tangible

Tasks

- Find and indicate a range of values
- Find and sort values
- Find and compare values

Measures

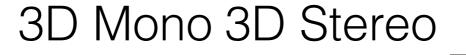
- Time
- Error rate



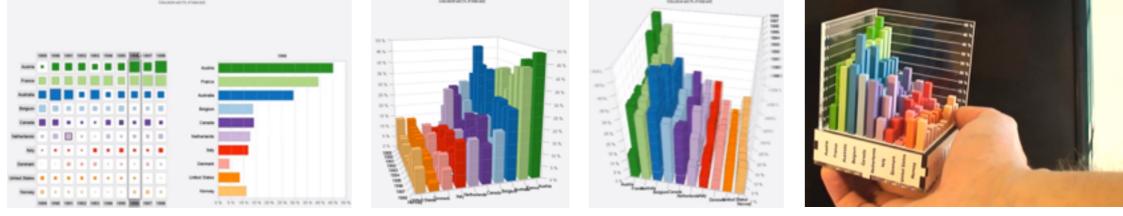
Users are:

- Around 20% faster with Tangible than with 3D
- Around 40% faster with 2D than with Tangible
 - however, effect weaker if the task cannot be solved by one 2D cut

Tangible



2D



Among possible explanation: Touch & Proprioception

3D mono/stereo	Tangible
sequential: rotate; mark; rotate; etc.	parallel: rotate // mark*
occluded bars impossible to reach	occluded bars reachable
with the mouse cursor	with the fingers
mouse cursor	proprioception compensate for
does not occlude the bars	fingers that occlude the bars

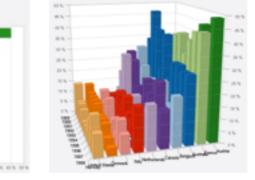
Proprioception

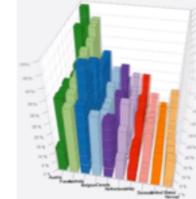
Definition:

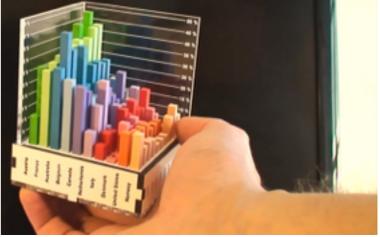
- Perception of our own body
- Sense of the relative position of our limbs through our skin, muscle, joints and inner ear

Tangible User Interfaces: What are they good for? D 3D Mono 3D Stereo Tangible







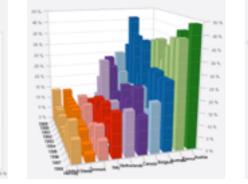


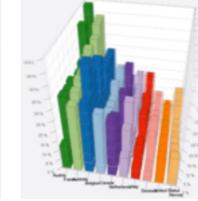
Among possible explanation: Direct rotation

3D mono/stereo	Tangible
"Indirect" rotation (mapped to x and y axis of mouse)	"Direct" rotation

Tangible User Interfaces: What are they good for? D 3D Mono 3D Stereo Tangible





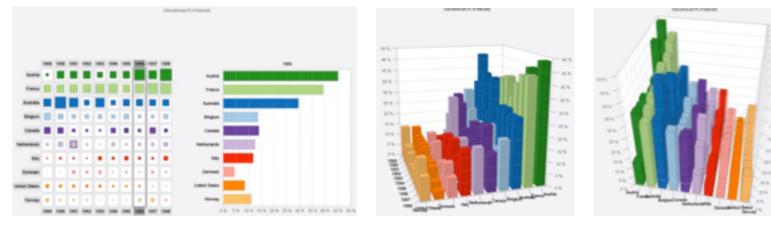




Among possible explanation: Visual Realism

	3D mono/stereo	Tangible
Resolution	1920 x 1080 px for 23"	0.5mm
Stereoscopic cues (Images L and R different)	no / yes	yes
Accomodation cues	at screen distance	at any distance
Shading and shadows	computer-generated	natural
Texture	none	spray paint imperfections

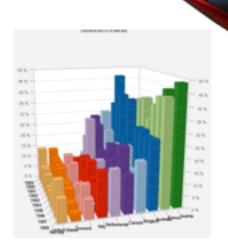
Tangible User Interfaces: What are they good for? D 3D Mono 3D Stereo Tangible





Impact of all possible explanations?

- Touch & Proprioception?
- Direct rotation?
- Visual Realism?



3D Mono & Indirect mouse rotation & No bar marking

Tangible Direct rotation & Touch



3D Mono & Prop-based direct rotation & No bar marking

Direct rotation

Tangible Direct rotation &

No touch



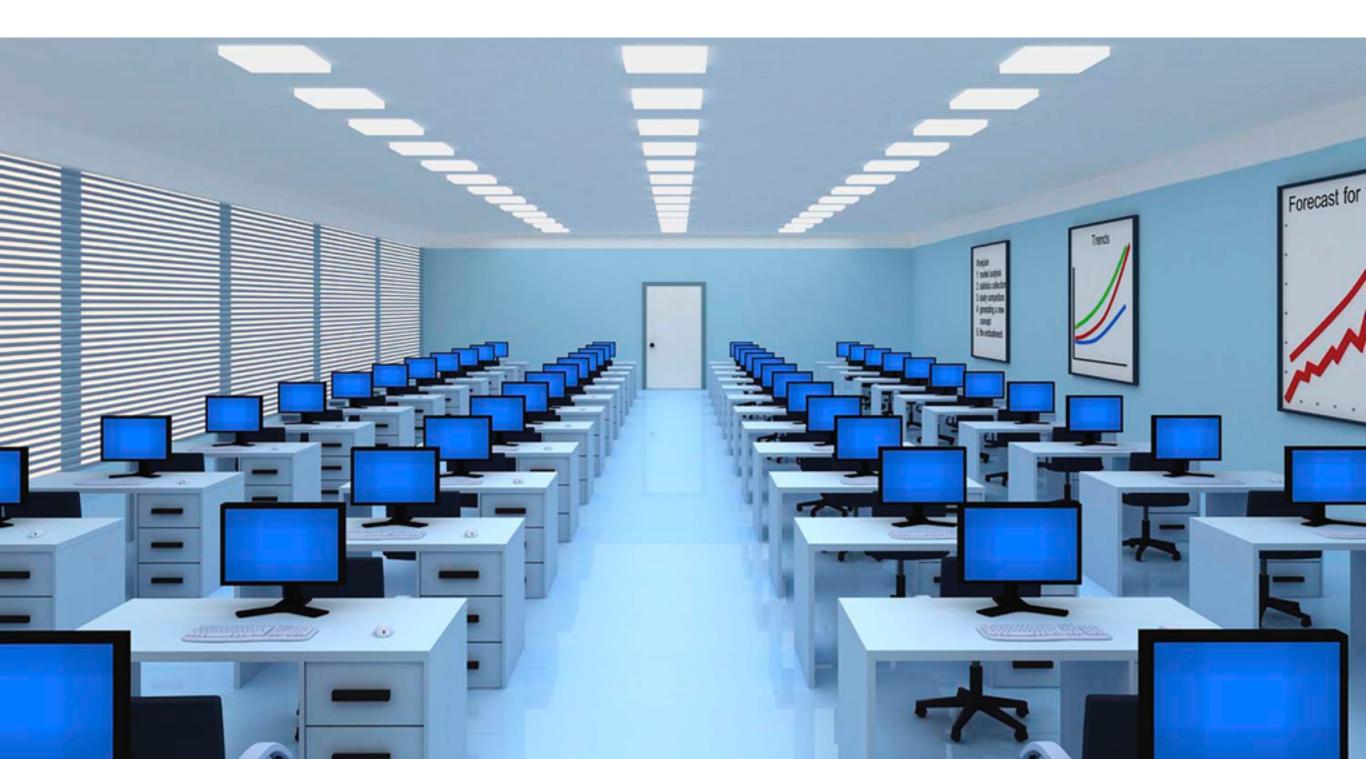
Touch &

Proprioception

Visual realism

- Direct rotation: very little faster compared to indirect rotation
- Visual Realism: around 13% faster compared to onscreen
- Touch & Proprioception: around 15% faster than no touch
 - unload cognitive effort into a physical action

Tangible User Interfaces What are their limitations?

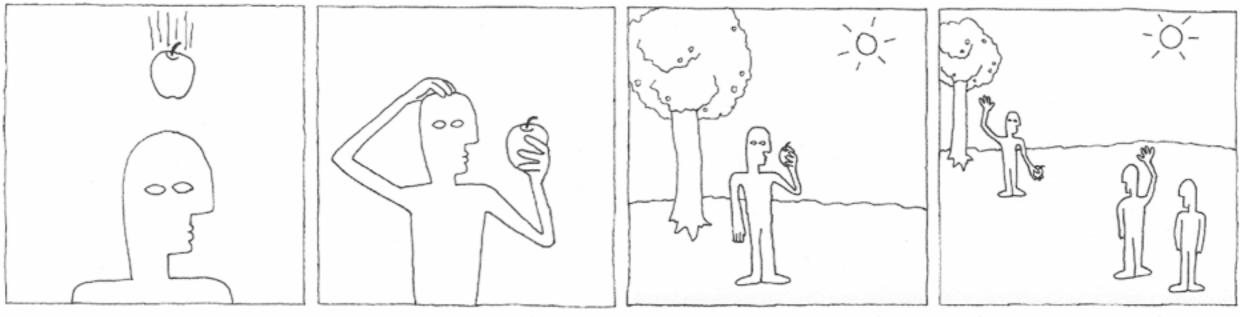


- Dynamicity, Flexibility
- Price

- Reality based interaction
 - Compromise with software when it brings benefit

http://dl.acm.org/citation.cfm?doid=1357054.1357089

- Interface design
 - build on 4 themes (= human capabilities) from the "real" world
 - compromise with 6 tradeoffs in order to reach design goal

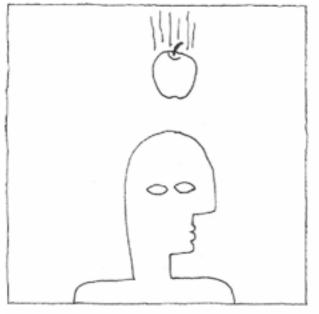


Naïve Physics

Body Awareness & Skills

Environment Awareness & Skills

Social Awareness & Skills



Naïve Physics

E.g., gravity, friction, velocity

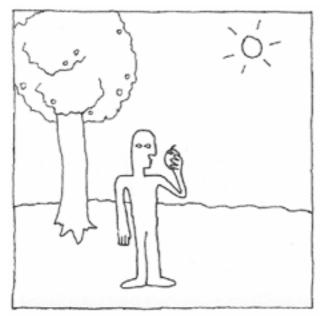
Example of interfaces using users' knowledge of naive physics?



Body Awareness & Skills

E.g., relative position of body parts, range of motion, skills to coordinate movements (to walk, kick a ball)

Example of interfaces using users' body awareness and skills?



Environment Awareness & Skills

E.g., horizon gives a sense of directional information, lighting and shadow provide depth cues

Example of interfaces using users' environment awareness and skills?



Social Awareness & Skills

E.g., verbal and non-verbal communication, exchange objects, ability for collaboration

Example of interfaces using users' social awareness and skills?

Reality Based Interaction: Six tradeoffs

Expressive power

ability to perform a variety of tasks within the application domain

Efficiency

ability to perform a task rapidly

Versatility

ability to perform many tasks from different application domains

Ergonomics

ability to perform a task without physical injury or fatigue

Accessibility

ability to perform a task when handicapped

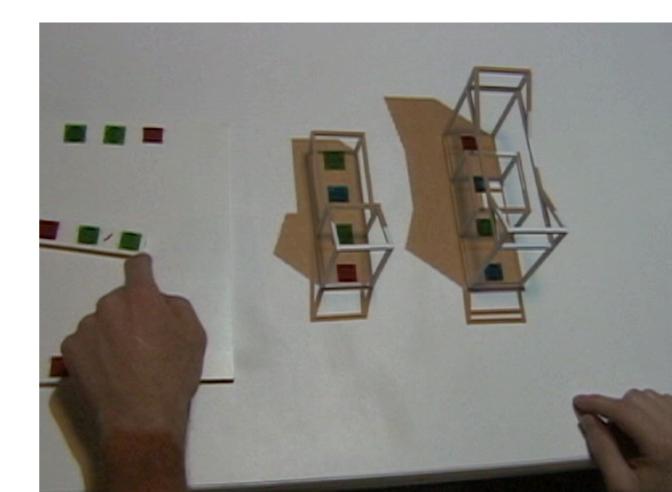
Practicality

(designers) ability to produce the system

Case study: URP

What themes does URP use?

- Naive Physics
- Body
- Environment
- Social Awareness



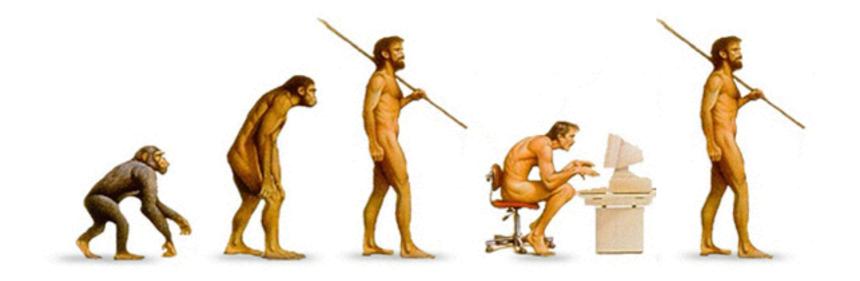
What does URP sacrifice for which benefit?

- Expressive power
- Efficiency
- Versatility
- Ergonomics
- Accessibility
- Practicality

- Software mouse+touch GUI took over
- Tangible might be coming back
 E.g., induction hub
 with removable magnetic tangible knob
- New and Open research areas that bring tangibles closer to software



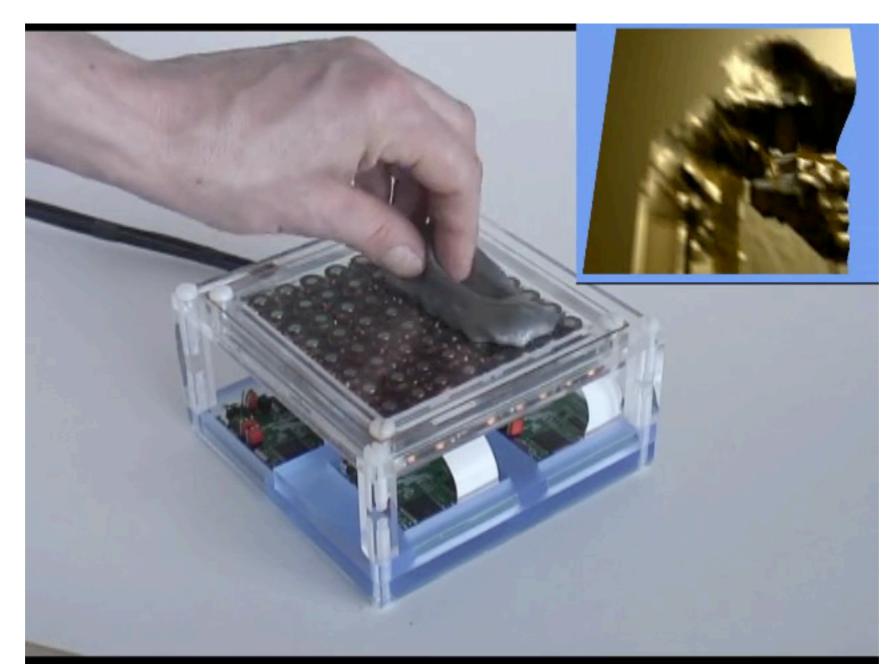
How can we benefit again from Tangibility?



BREAK

• Focus group

A Reconfigurable Ferromagnetic Input Device

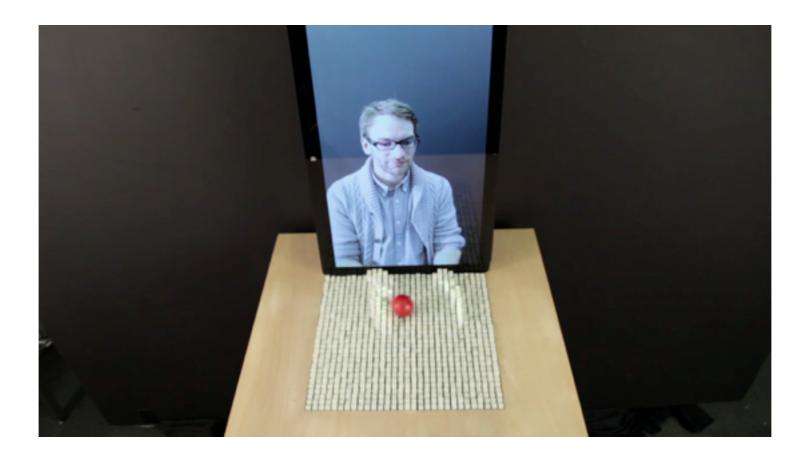


SandScape

Illuminating Clay



Dynamically changeable buttons: http://www.youtube.com/watch?v=Smai_Z_galE





non-elastic airbag + plain paper



Shutters with shape memory alloy



Dynamicity & Flexibility: Shape with nanoscopic cells

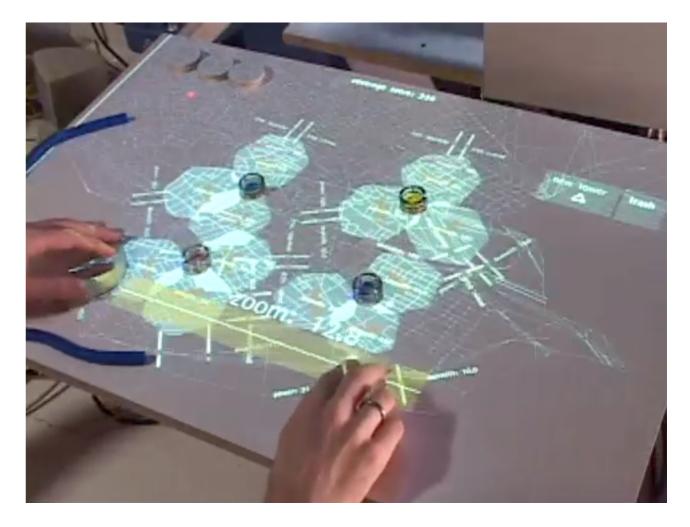
Bacillus Subtilis Natto is a bacteria that has been widely used to ferment food

Dynamicity & Flexibility: 2D location

Actuated workBench

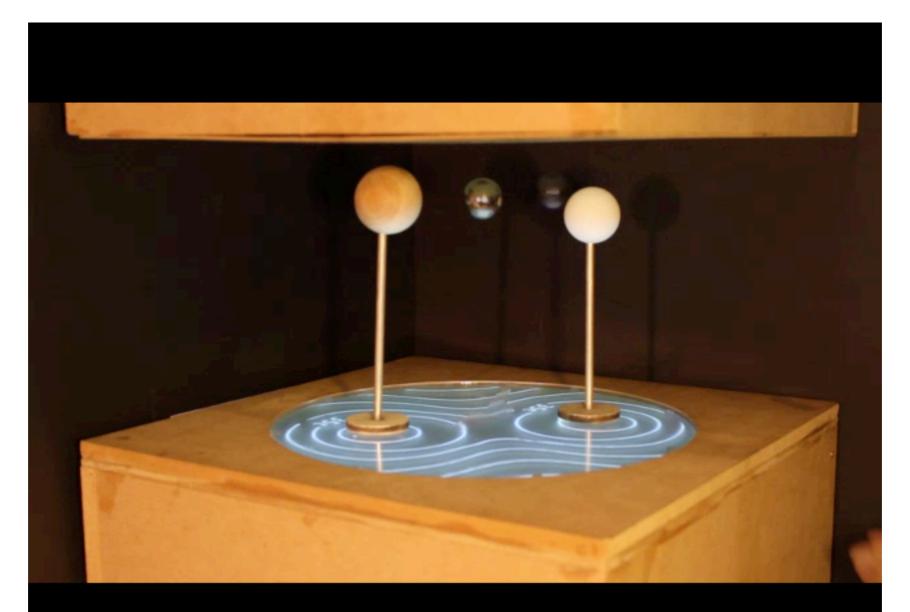






Dynamicity & Flexibility: 3D location

(several technologies)



Dynamicity & Flexibility: Stiffness



Dynamicity & Flexibility: Stiffness

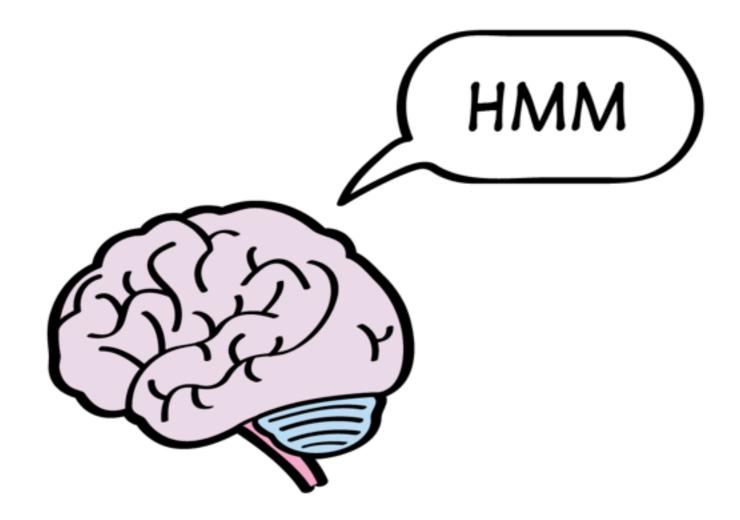
3D Printing Pneumatic Device Controls with Variable Activation Force Capabilities

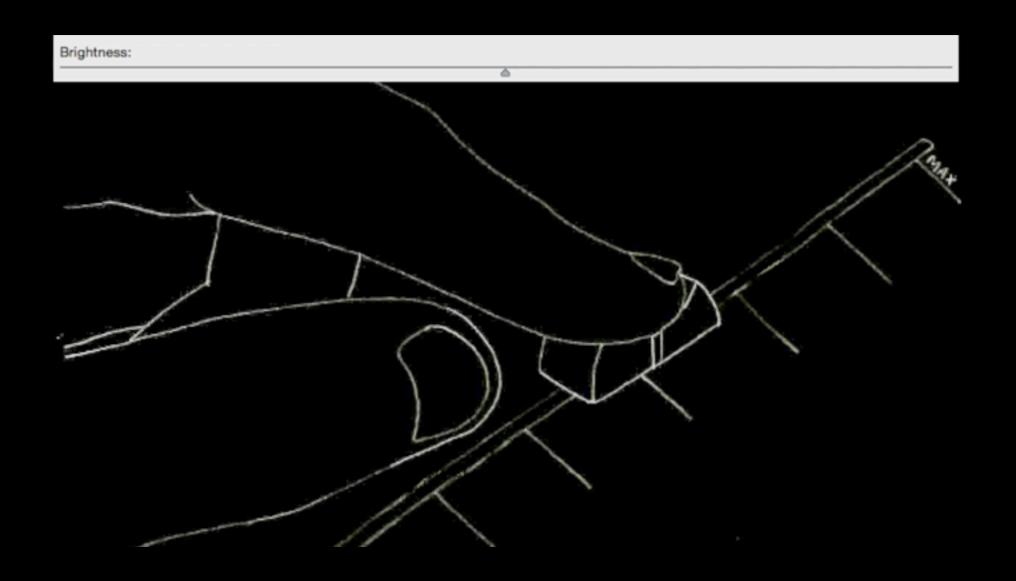
https://youtu.be/-4gFYvhkz0Y

Dynamicity & Flexibility: Weight

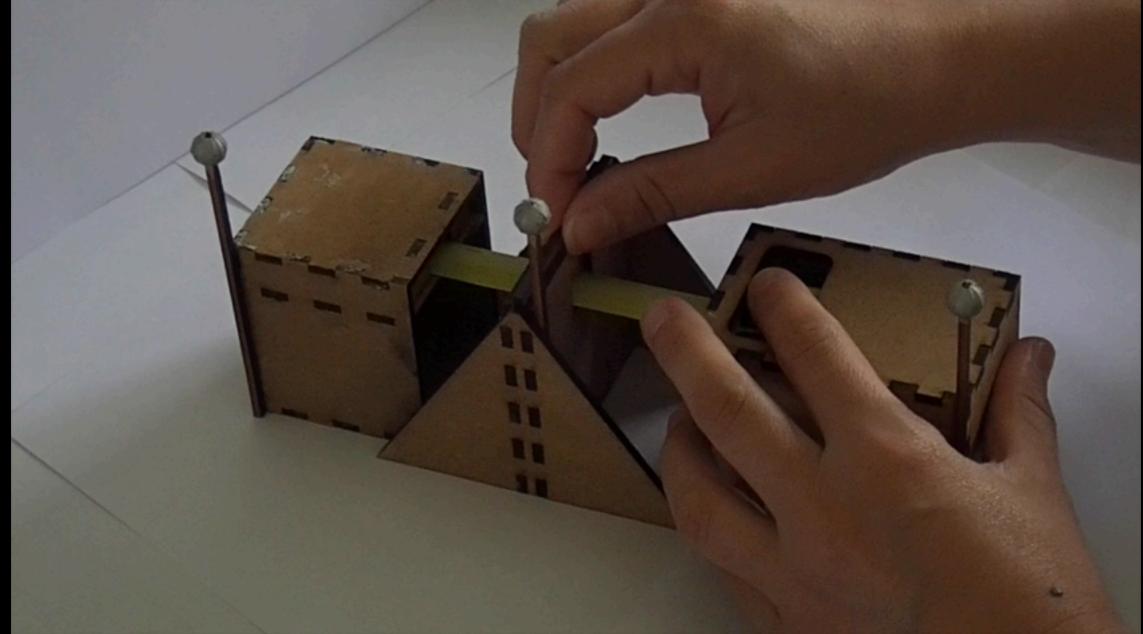
Mechanism: Mass Transfer with Liquid Metal

Dynamicity & Flexibility: What is is good for?





Prototype



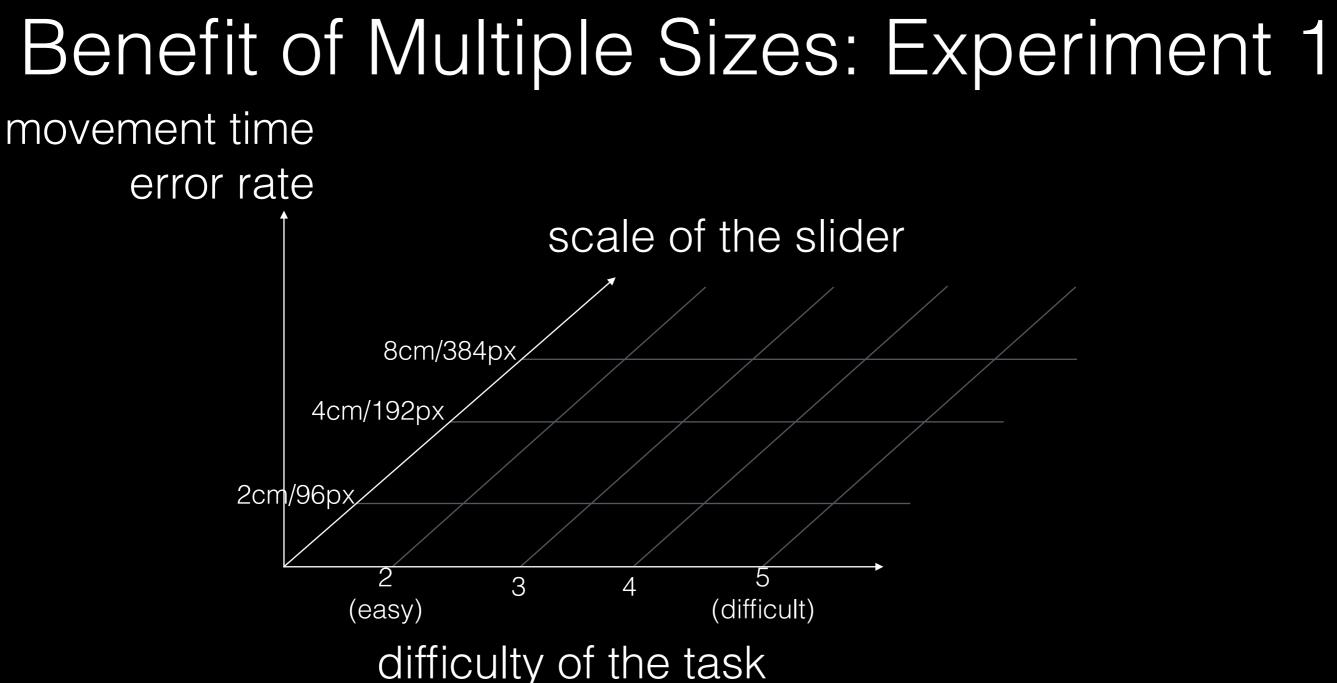
127

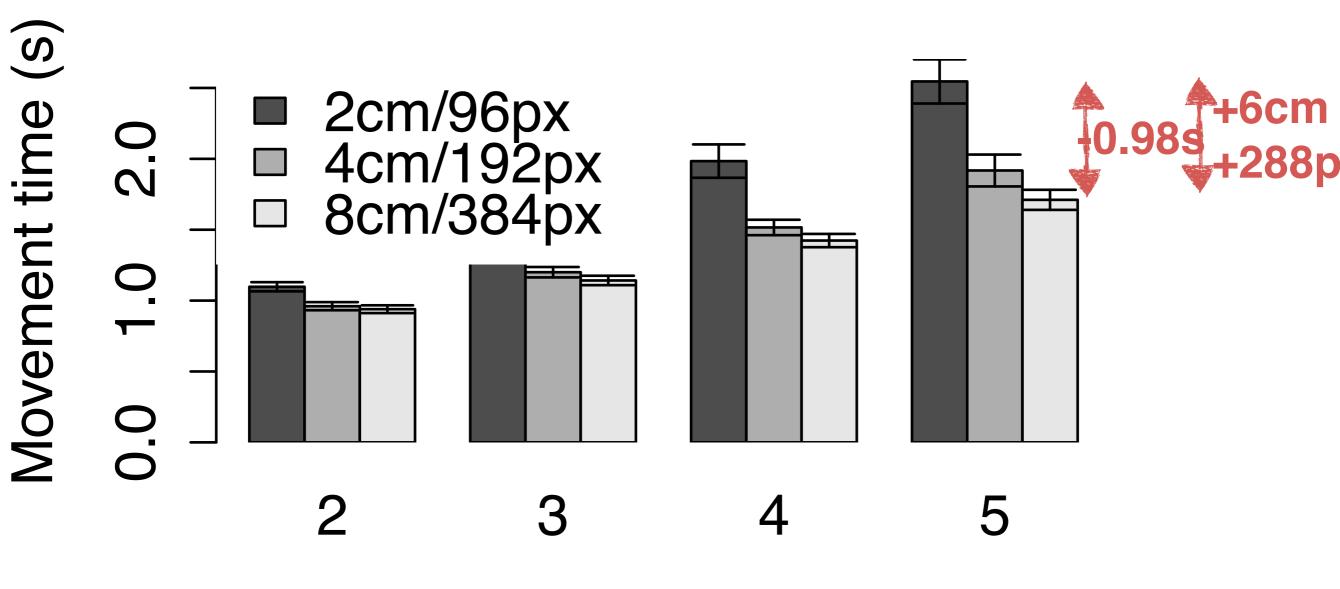
Prototype

resolution: 2822 dpi

Benefit of Multiple Sizes: Experiment 1

How much more efficient are users with a large slider than a small slider?





Index of Difficulty (easy to difficult)

Zoomed in is better

not possible when workspace is restricted



Drawback of resizing: Experiment 2

Impact of resizing on performance

Drawback of resizing: Experiment 2

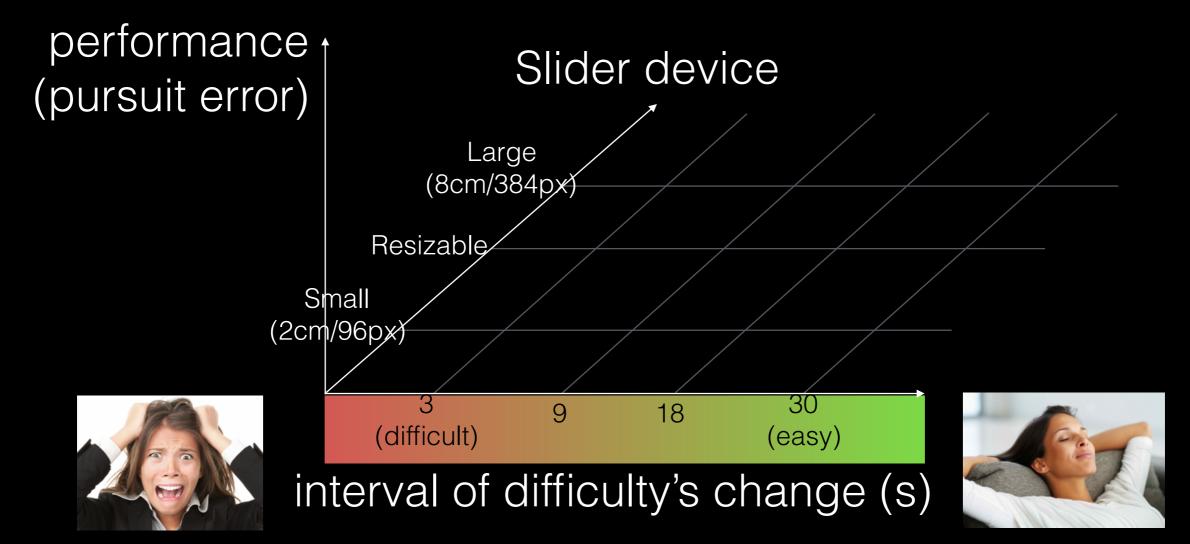




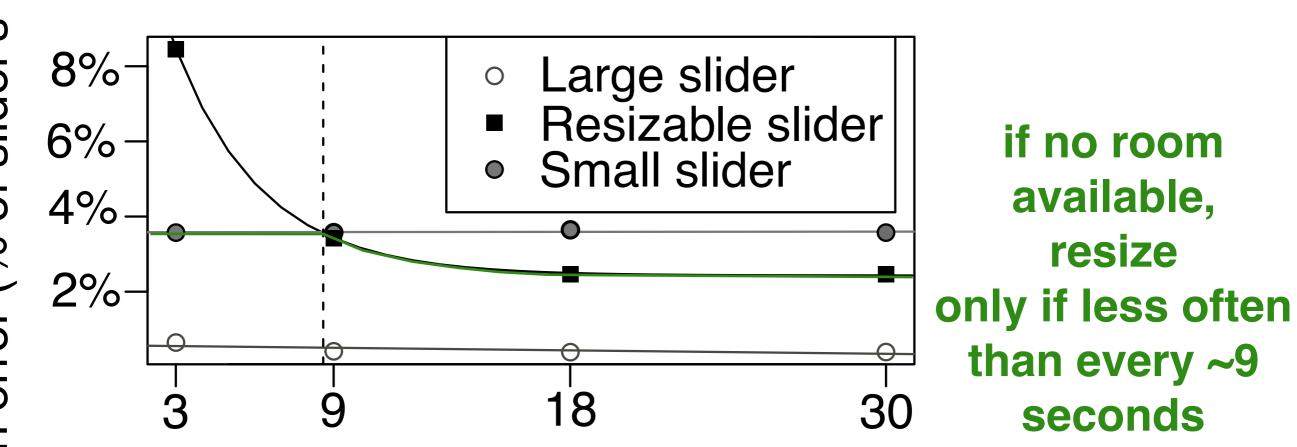


134

Drawback of resizing: Experiment



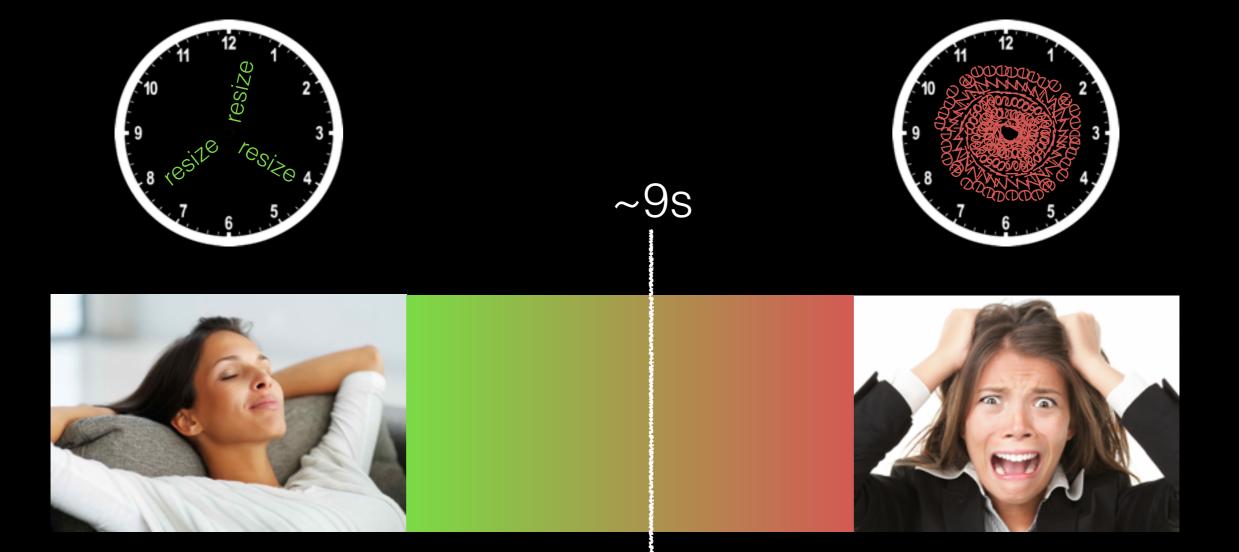
Median error (% of slider's range)



Interval of difficulty change (s)

136

Resizing brings benefits If less often than every ~9 seconds



Future of Tangible Interaction

Flexibility will not be software's monopoly and will reach Tangibles



Radical Atoms & Perfect Red

Claytronics

Future of Tangible Interaction

Focus group